

# Robot user interface promoting high speed learning of operation skill by a control of operation preference

メタデータ	言語: jpn 出版者: 公開日: 2020-12-10 キーワード (Ja): キーワード (En): 作成者: Watanabe, Tetsuyou メールアドレス: 所属:
URL	<a href="https://doi.org/10.24517/00059800">https://doi.org/10.24517/00059800</a>

This work is licensed under a Creative Commons Attribution-NonCommercial-ShareAlike 3.0 International License.



[◀ Back to previous page](#)

# Robot user interface promoting high speed learning of operation skill by a control of operation preference

Publicly

<b>Project Area</b>	Cognitive Interaction Design: A Model-Based Understanding of Communication and its Application to Artifact Design
<b>Project/Area Number</b>	17H05858
<b>Research Category</b>	Grant-in-Aid for Scientific Research on Innovative Areas (Research in a proposed research area)
<b>Allocation Type</b>	Single-year Grants
<b>Review Section</b>	Complex systems
<b>Research Institution</b>	Kanazawa University
<b>Principal Investigator</b>	渡辺 哲陽 金沢大学, フロンティア工学系, 教授 (80363125)
<b>Project Period (FY)</b>	2017-04-01 – 2019-03-31
<b>Project Status</b>	Granted (Fiscal Year 2018)
<b>Budget Amount *help</b>	¥11,570,000 (Direct Cost: ¥8,900,000、 Indirect Cost: ¥2,670,000) Fiscal Year 2018: ¥5,980,000 (Direct Cost: ¥4,600,000、 Indirect Cost: ¥1,380,000) Fiscal Year 2017: ¥5,590,000 (Direct Cost: ¥4,300,000、 Indirect Cost: ¥1,290,000)
<b>Keywords</b>	ユーザーインターフェース / 知能機械 / 知能ロボティクス / 操作習熟 / 操作嗜好性 / ユーザインターフェース / 知能ロボティックス

URL: <https://kaken.nii.ac.jp/grant/KAKENHI-PUBLICLY-17H05858/>

Published: 2017-04-28 Modified: 2018-07-26