操作嗜好性を制御して高効率操作習熟を実現するロボット操作システム

Robot user interface promoting high speed learning of operation skill by a control of operation preference

Publicly

All

Project Area	Cognitive Interaction Design: A Model-Based Understanding of Communication and its Application to Artifact Design
Project/Area Number	17H05858
Research Category	Grant-in-Aid for Scientific Research on Innovative Areas (Research in a proposed research area)
Allocation Type	Single-year Grants
Review Section	Complex systems
Research Institution	Kanazawa University
Principal Investigator	**渡辺 哲陽** 金沢大学, フロンティア工学系, 教授 (80363125)
Project Period (FY)	**2017-04-01 – 2019-03-31**
Project Status	Granted (Fiscal Year 2018)
Budget Amount *help	**¥11,570,000 (Direct Cost: ¥8,900,000、Indirect Cost: ¥2,670,000)** Fiscal Year 2018: ¥5,980,000 (Direct Cost: ¥4,600,000、Indirect Cost: ¥1,380,000) Fiscal Year 2017: ¥5,590,000 (Direct Cost: ¥4,300,000、Indirect Cost: ¥1,290,000)
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