A Linear Time Algorithm for Constructing Proper－Path－Decomposition of Width Two

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# A Linear Time Algorithm for Constructing Proper-PathDecomposition of Width Two 

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#### Abstract

SUMMARY The problem of constructing the proper-pathdecomposition of width at most 2 has an application to the efficient graph layout into ladders. In this paper, we give a linear time algorithm which, for a given graph with maximum vertex degree at most 3 , determines whether the proper-pathwidth of the graph is at most 2 , and if so, constructs a proper-pathdecomposition of width at most 2 . key words: proper-path-decomposition, proper-pathwidth, pathwidth, graph layout


## 1. Introduction

The pathwidth of a graph $G$ is the minimum value of $k$ such that $G$ can be obtained from a sequence of graphs $H_{1}, H_{2}, \ldots, H_{r}$ each of which has at most $k+1$ vertices, by identifying some vertices of $H_{i}$ pairwise with some of $H_{i+1}(1 \leqq i<r)$ [5]. The sequence $H_{1}, H_{2}, \ldots, H_{r}$ is called a path-decomposition of $G$ with width $k$. The proper-pathwidth is introduced in [6] as a variant of the pathwidth. The (proper-)pathwidth is closely related to other graph parameters such as cutwidth, topological bandwidth, and search numbers. It is NP-complete to decide, given a graph $G$ and an integer $k$, whether the (proper-)pathwidth of $G$ is at most $k$, while the problem is in P if $k$ is a fixed integer. It is shown in [2] that if the pathwidth of a graph $G$ is bounded by a fixed integer $k$ then a path-decomposition of $G$ with width $k$ can be constructed in polynomial time. On the other hand, no polynomial time algorithm is known for the problem of constructing a proper-path-decomposition of width $k$ for a graph with proper-pathwidth bounded by a fixed integer $k \geqq 2$.

The graphs which can be laid out into ladders are characterized in terms of the proper-pathwidth of graphs [3]. It is known that finding a proper-pathdecomposition of width 2 for a graph with maximum vertex degree 3 and proper-pathwidth 2 is crucial to lay out such a graph into the ladder [3].

The purpose of this paper is to give a linear time algorithm for constructing a proper-path-decomposition of width 2 for a graph with maximum vertex degree 3 and proper-pathwidth 2.

[^0]It is shown in [1] that if the treewidth of a graph $G$ is bounded by a fixed integer $k$ then a treedecomposition of $G$ with width $k$ can be constructed in linear time and, by using this fact and the result of [2], a path-decomposition of $G$ with minimum width can also be constructed in linear time. However, this result cannot be generalized immediately to our problem of constructing proper-path-decompositions of minimum width since there exist graphs with the proper-pathwidth more than the pathwidth because of an additional condition ((e) in Condition 1 given in Sect. 2) which is introduced to define the proper-pathdecomposition.

The rest of the paper is organized as follows. Some definitions are given in Sect. 2. In Sect. 3, we give a characterization of graphs with maximum vertex degree 3 and proper-pathwidth 2. We give in Sect. 4 the proof of the characterization and an algorithm for constructing a proper-path-decomposition of width 2 .

## 2. Preliminaries

Let $G$ be a graph and let $V(G)$ and $E(G)$ denote the vertex set and edge set of $G$, respectively. $\Gamma_{G}(v)$ is the set of edges incident to a vertex $v$ in $G$. $\left|\Gamma_{G}(v)\right|$ is called the degree of $v$ and denoted by $\operatorname{deg}_{G}(v)$. Let $\Delta(G)=\max \left\{\operatorname{deg}_{G}(v) \mid v \in V(G)\right\} . \quad N_{G}(v)$ is the set of vertices adjacent to a vertex $v$ in $G$. For $U \subseteq V(G)$, let $G[U]$ be the subgraph of $G$ induced by $U$, and let $G-U$ denote $G[V(G)-U]$. Similarly, for $S \subseteq E(G)$, let $G[S]$ be the subgraph of $G$ induced by $S$, and let $G-S$ denote the graph obtained from $G$ by deleting $S$. For graphs $G$ and $H, G \cup H$ is the graph with vertex set $V(G) \cup V(H)$ and edge set $E(G) \cup E(H)$, and $G \cap H$ is the graph with vertex set $V(G) \cap V(H)$ and edge set $E(G) \cap E(H)$. Although a path is a graph, we often denote a path by a sequence of vertices in which consecutive two vertices are adjacent in the path.

A vertex $v$ of $G$ is a cut vertex if $E(G)$ can be partitioned into two nonempty subsets $E_{1}$ and $E_{2}$ such that $G\left[E_{1}\right]$ and $G\left[E_{2}\right]$ have just the vertex $v$ in common. A connected graph that has no cut vertices is called a block. Every block with at least three vertices is 2 -connected. A block of a graph is a subgraph that is a block and is maximal with respect to this property.

A graph is outer planar if it has a planar drawing


Fig. 1 Minimal forbidden minors for $\mathcal{P}_{2}$
in which the outer region includes all of its vertices. An edge is outer if it is included in the outer region, and is inner otherwise. A cycle $C$ of an outer planar graph $G$ is an end-region of $G$ if $C=G[V(C)]$ and $C$ has at most one inner edge. Any 2-connected outer planar graph has at least one end-region, and it has at least two end-regions if it has an inner edge.

For a graph $G$, a sequence $\mathcal{X}=\left(X_{1}, \ldots, X_{r}\right)$ of subsets of $V(G)$ is called a proper-path-decomposition of $G$ if $\mathcal{X}$ satisfies the following conditions.

## Condition 1:

(a) $X_{i} \nsubseteq X_{j}(i \neq j)$;
(b) $\bigcup_{1 \leqq i \leqq r} X_{i}=V(G)$;
(c) for any $(u, v) \in E(G)$, there exists an $i$ such that $u, v \in X_{i}$;
(d) for all $a, b$, and $c$ with $1 \leqq a \leqq b \leqq c \leqq r$, $X_{a} \cap X_{c} \subseteq X_{b} ;$
(e) for all $a, b$, and $c$ with $1 \leqq a<b<c \leqq r$, $\left|X_{a} \cap X_{c}\right| \leqq\left|X_{b}\right|-2$ if $\left|X_{b}\right| \geqq 2$.

The width of $\mathcal{X}$ is $\max _{1 \leqq i \leqq r}\left|X_{i}\right|-1$. The properpathwidth of $G$ is the minimum width over all proper-path-decompositions of $G$, and denoted by $p p w(G)$. A proper-path-decomposition is said to be optimal if it has width of $\operatorname{ppw}(G)$. A proper-path-decomposition of width $k$ is called a $k$-proper-path-decomposition.

A graph $H$ is a minor of a graph $G$ if $H$ is isomorphic to a graph obtained from a subgraph of $G$ by contracting edges. A family $\mathcal{F}$ of graphs is said to be minor-closed if the following condition holds: If $G \in \mathcal{F}$ and $H$ is a minor of $G$ then $H \in \mathcal{F}$. A graph $G$ is a minimal forbidden minor for a minor-closed family $\mathcal{F}$ of graphs if $G \notin \mathcal{F}$ and any proper minor of $G$ is in $\mathcal{F}$. $\mathcal{F}$ is characterized by the minimal forbidden minors for $\mathcal{F}$. That is, a graph $G$ is in $\mathcal{F}$ if and only if no minimal forbidden minor for $\mathcal{F}$ is a minor of $G$. For a positive integer $k$, the family $\mathcal{P}_{k}$ of graphs with proper-pathwidth at most $k$ is minor-closed. $K_{3}$ and $K_{1,3}$ are the minimal forbidden minors for $\mathcal{P}_{1}[6]$, and 36 graphs are known as the minimal forbidden minors for $\mathcal{P}_{2}$ [7]. The five minimal forbidden minors for $\mathcal{P}_{2}$ shown in Fig. 1 will be used in Sect. 4.

## 3. Characterization

In this section, we characterize graphs with maximum vertex degree 3 and proper-pathwidth 2.

Suppose that $G^{\prime}$ is a graph obtained from a graph $G$ by deleting self-loops and replacing multiple edges with a single edge. A proper-path-decomposition of $G^{\prime}$ is also that of $G$, and vice versa, by definition. Therefore, an optimal proper-path-decomposition of $G^{\prime}$ is also that of $G$. An optimal proper-path-decomposition of a graph can be obtained by concatenating optimal proper-path-decompositions of connected components. From these facts, we assume that the graphs considered in the rest of the paper are simple and connected.

A cut vertex of a graph $G$ is called a connection point of $G$ if the vertex is contained in a 2 -connected block of $G$. Since a connection point of $G$ is a cut vertex of $G, E(G)$ can be partitioned into disjoint sets $E_{1}, \ldots, E_{l}$ such that $G\left[E_{i}\right]$ and $G\left[E_{j}\right]$ share at most one connection point of $G$ for any $i$ and $j$ with $1 \leqq i<j \leqq l$. Let $\mathcal{D}=\left\{G\left[E_{i}\right] \mid 1 \leqq i \leqq l\right\}$. We define that $\mathcal{H}$ is the set of 2 -connected components in $\mathcal{D}$. A component of $\mathcal{D}-\mathcal{H}$ is called a path component of $G$ if the component is a path. $\mathcal{P}$ denotes the set of path components of $G$. A component of $\mathcal{D}-(\mathcal{H} \cup \mathcal{P})$ is called a tree component of $G . \mathcal{T}$ denotes the set of tree components of $G$.

The following characterization for trees with proper-pathwidth at most $k$ is given in [9].
Lemma A: For a tree $T$ and an integer $k \geqq 2$, $\operatorname{ppw}(T) \leqq k$ if and only if there exists a path $P$ in $T$ such that $p p w(T-V(P)) \leqq k-1$.
$k$-spine of $T$ is a path satisfying the condition of Lemma A.

The following is the main theorem of the paper.
Theorem 1: For a graph $G$ with $\Delta(G) \leqq 3$, $\operatorname{ppw}(G) \leqq 2$ if and only if $G$ has a sequence $\mathcal{C}=$ $\left(C_{1}, C_{2}, \ldots, C_{m}\right)$ of distinct components in $\mathcal{D}$ and a sequence $\mathcal{A}=\left(a_{0}, a_{1}, \ldots, a_{m}\right)$ of distinct vertices of $G$ such that the following condition is satisfied. Let $\mathcal{D}^{\prime}=\mathcal{D}-\left\{C_{i} \mid 1 \leqq i \leqq m\right\}$.

## Condition 2:

(a) $V\left(C_{i}\right) \cap V\left(C_{i+1}\right)=\left\{a_{i}\right\}$ for $1 \leqq i<m$, $a_{0} \in V\left(C_{1}\right)$, and $a_{m} \in V\left(C_{m}\right)$.
(b) $\operatorname{deg}_{G}\left(a_{0}\right) \leqq 2$ and $\operatorname{deg}_{G}\left(a_{m}\right) \leqq 2$.
(c) For $1 \leqq i \leqq m$, if $C_{i} \in \mathcal{T}$ then the path in $C_{i}$ connecting $a_{i-1}$ and $a_{i}$ is a 2 -spine of $C_{i}$.
(d) For $1 \leqq i \leqq m$, if $C_{i} \in \mathcal{H}$ then $C_{i}$ is an outer planar graph with at most two end-regions. Moreover, each end-region contains $a_{i-1}$ or $a_{i}$.
(e) $\mathcal{D}^{\prime} \subseteq \mathcal{P}$.
(f) There exists a one-to-one mapping $f: \mathcal{D}^{\prime} \rightarrow$ $\{i \mid 1 \leqq i \leqq m\} \times\{0,1\}$ satisfying the following statement.

For $P \in \mathcal{D}^{\prime}, f(P)=(i, j)$ if and only if $C_{i} \in \mathcal{H}$ and there exists an end-vertex $x$ of $P$ such that $\left(x, a_{i-j}\right) \in E\left(C_{i}\right) .(*)$

In the following section, we give a constructive proof for Theorem 1, and based on the proof, we describe a linear time algorithm which, given a graph $G$ with $\Delta(G) \leqq 3$, determines whether $p p w(G) \leqq 2$, and if so, constructs a proper-path-decomposition of width at most 2 of $G$.

## 4. Proof and Algorithm

We first prove the theorem for a special case of $|\mathcal{D}|=1$. We prove the theorem for trees and 2 -connected graphs in Sect. 4.1 and 4.2, respectively. The proof for general case is given in Sect. 4.3. We also give in Sect. 4.3 an algorithm for general graphs.

For a sequence $\mathcal{X}=\left(X_{1}, X_{2}, \ldots, X_{r}\right)$ of elements, $X_{1}$ and $X_{r}$ are called the head of $\mathcal{X}$ and its tail, respectively. We denote the sequence without elements by nul. For sequences $\mathcal{X}=\left(X_{1}, X_{2}, \ldots, X_{r}\right)$ and $\mathcal{Y}=\left(Y_{1}, Y_{2}, \ldots, Y_{q}\right)$, we define that $\mathcal{X}+\mathcal{Y}=$ $\left(X_{1}, X_{2}, \ldots, X_{r}, Y_{1}, Y_{2}, \ldots, Y_{q}\right)$. For a sequence $\mathcal{X}=$ $\left(X_{1}, X_{2}, \ldots, X_{r}\right)$ of subsets of a set $\Omega$ and $W \subseteq \Omega$, we define that $\mathcal{X} \cup W=\left(X_{1} \cup W, X_{2} \cup W, \ldots, X_{r} \cup W\right)$ and $\mathcal{X} \cap W=\left(X_{1} \cap W, X_{2} \cap W, \ldots, X_{r} \cap W\right)$.

### 4.1 Binary Trees

Theorem 1 is immediate for binary trees by Lemma A. An algorithm for constructing optimal proper-pathdecompositions of trees is shown in [8]. Since this algorithm computes $p p w(T)$ in $O(N)$ time for an $N$ vertex tree $T$ and provides an optimal proper-pathdecomposition of $T$ in $O(N p p w(T))$ time, we can construct a 2-proper-path-decomposition of $T$ with $\operatorname{ppw}(T)=2$ in linear time.

In this subsection, we show algorithms for constructing a proper-path-decomposition of a binary tree with width at most 2 satisfying some conditions. These algorithms will be used to construct an algorithm for general graphs.
Lemma 2: For a path $P=\left(p_{0}, \ldots, p_{l}\right)$, there exists a 1-proper-path-decomposition $\mathcal{X}=\left(X_{1}, \ldots, X_{r}\right)$ of $P$ such that $p_{0} \in X_{1}$ and $p_{l} \in X_{r}$.
Proof: Let $\mathcal{X}=\left(X_{1}, \ldots, X_{l}\right)$ with $X_{i}=\left\{p_{i-1}, p_{i}\right\}$ $(1 \leqq i \leqq l)$ if $l \geqq 1, \mathcal{X}=\left(\left\{p_{0}\right\}\right)$ otherwise. $\mathcal{X}$ is clearly a desired proper-path-decomposition.
Algorithm PPD_PATH shown in Fig. 2 is the formal description of the procedure written in the proof of Lemma 2. Trivially, PPD_PATH can be executed in linear time.
Lemma 3: For a binary tree $T$ with $p p w(T)=$ 2 and its 2 -spine $P=\left(p_{0}, \ldots, p_{l}\right)$ such that

Procedure PPD_PATH ( $P$ )
$\left.\begin{array}{ll}\text { Input: } & \text { a path } P=\left(p_{0}, p_{1}, \ldots, p_{l}\right) ; \\ \text { Output: } & \text { a } 1 \text {-proper-path-decomposition }\left(X_{1}, X_{2}, \ldots, X_{r}\right) \\ & \text { of } P \text { such that } p_{0} \in X_{1} \text { and } p_{l} \in X_{r} ;\end{array}\right]$
. if $l=0$ then return $\left(\left\{p_{0}\right\}\right)$;
. for each $1 \leqq i \leqq l$ do
$X_{i}:=\left\{p_{i-1}, p_{i}\right\} ;$
endfor ;
return $\left(X_{1}, X_{2}, \ldots, X_{l}\right)$;
End
Fig. 2 Algorithm for constructing a 1-proper-pathdecomposition of a path.
$\operatorname{deg}_{T}\left(p_{0}\right)=\operatorname{deg}_{T}\left(p_{l}\right)=1$, there exists a 2 -proper-path-decomposition $\mathcal{X}=\left(X_{1}, \ldots, X_{r}\right)$ of $T$ such that $p_{0} \in X_{1}-\bigcup_{1<i \leqq r} X_{i}$ and $p_{l} \in X_{r}-\bigcup_{1 \leqq i<r} X_{i}$.
Proof: Since $P$ is a 2 -spine of $T$, it follows from Lemma A that $\operatorname{ppw}(T-V(P)) \leqq 1$. Thus, each connected component of $T-V(P)$ is a path. For $0<i<l$, at most one connected component $P_{i}$ of $T-V(P)$ has a vertex adjacent to $p_{i}$ since $\Delta(T) \leqq 3$. Let $I=\left\{i \mid 0<i<l, \operatorname{deg}_{T}\left(p_{i}\right)=3\right\}$. We define the sequence $\mathcal{X}$ of subsets of $V(T)$ as follows:

$$
\mathcal{X}=\left(S_{1}\right)+\mathcal{Y}_{1}+\left(S_{2}\right)+\cdots+\left(S_{l-1}\right)+\mathcal{Y}_{l-1}+\left(S_{l}\right),
$$

$$
\text { where for } 1 \leqq i \leqq l \text {, }
$$

$$
S_{i}= \begin{cases}\left\{p_{i-1}, p_{i}\right\} \cup V\left(P_{i}\right) \\ \left\{p_{i-1}, p_{i}\right\} & \text { if } i \in I \text { and }\left|V\left(P_{i}\right)\right|=1\end{cases}
$$

for $1 \leqq i<l$,

$$
\mathcal{Y}_{i}= \begin{cases}\text { PPD_PATH }\left(P_{i}\right) \cup\left\{p_{i}\right\} \\ \text { nul } & \text { if } i \in I \text { and }\left|V\left(P_{i}\right)\right| \geqq 2 \\ \text { otherwise }\end{cases}
$$

We show that $\mathcal{X}$ is a desired 2-proper-pathdecomposition. The following claim can be easily observed from the definition of $\mathcal{X}$.

## Claim 4:

1. $p_{0}$ and $p_{l}$ appear in $S_{1}$ and $S_{l}$, respectively.
2. For $0<i<l, p_{i}$ appears in $S_{i} \cap S_{i+1}$. Moreover, $p_{i}$ appears in every element of $\mathcal{Y}_{i}$ if $\mathcal{Y}_{i} \neq n u l$.
3. For $i \in I$ with $\left|V\left(P_{i}\right)\right| \geqq 2, v \in V\left(P_{i}\right)$ appears in at most two consecutive elements of $\mathcal{Y}_{i}$.
4. For $i \in I$ with $\left|V\left(P_{i}\right)\right|=1, v \in V\left(P_{i}\right)$ appears in $S_{i}$.

It is clear by Claim 4 that $\mathcal{X}$ satisfies (a), (b), and (c) in Condition 1. Moreover, $\mathcal{X}$ satisfies (d) in Condition 1 since we can observe that any vertex of $T$ appears in consecutive elements of $\mathcal{X}$. In what follows, we show that $\mathcal{X}$ satisfies (e) in Condition 1. If $X_{a} \cap X_{c}=\emptyset$ for all $a$ and $c$ with $1<a+1 \leqq c-1<r$ then the condition is clearly satisfied. Thus, we assume that there exist $a$

```
Procedure PPD_TREE ( \(T, P\) )
    Input: a binary tree \(T\);
        a 2 -spine \(P=\left(p_{0}, \ldots, p_{l}\right)\) of \(T\) such that
                \(\operatorname{deg}_{T}\left(p_{0}\right)=\operatorname{deg}_{T}\left(p_{l}\right)=1 ;\)
    Output: a proper-path-decomposition \(\left(X_{1}, \ldots, X_{r}\right)\) of \(T\)
                with width at most 2 such that \(p_{0} \in X_{1}-\)
                        \(\bigcup_{1<i \leqq r} X_{i}\) and \(p_{l} \in X_{r}-\bigcup_{1 \leqq i<r} X_{i} ;\)
```

    1. for \(i:=1\) to \(l-1\) do
        a. \(S_{i}:=\left\{p_{i-1}, p_{i}\right\} ;\)
        b. \(\mathcal{Y}_{i}:=n u l\);
        c. if \(\operatorname{deg}_{T}\left(p_{i}\right)=3\) then
                            i. let \(P_{i}\) be the connected component in \(T-V(P)\)
                which has a vertex adjacent to \(p_{i}\) in \(T\);
            ii. if \(\left|V\left(P_{i}\right)\right|=1\) then \(S_{i}:=\left\{p_{i-1}, p_{i}\right\} \cup V\left(P_{i}\right)\);
                else \(\mathcal{Y}_{i}:=\) PPD_PATH \(\left(P_{i}\right) \cup\left\{p_{i}\right\} ;\)
        endfor ;
    2. \(S_{l}:=\left\{p_{l-1}, p_{l}\right\}\);
    3. return \(\left(S_{1}\right)+\mathcal{Y}_{1}+\left(S_{2}\right)+\cdots+\left(S_{l-1}\right)+\mathcal{Y}_{l-1}+\left(S_{l}\right)\);
    End

Fig. 3 Algorithm for constructing a 2-proper-pathdecomposition of a binary tree with its 2 -spine.
and $c$ with $1<a+1 \leqq c-1<r$ such that $X_{a} \cap X_{c} \neq \emptyset$. Since any vertex in $V(T)-\left\{p_{i}\left|i \in I,\left|V\left(P_{i}\right)\right| \geqq 2\right\}\right.$ appears in at most two consecutive elements of $\mathcal{X}$, there exists $p_{i}$ such that $i \in I,\left|V\left(P_{i}\right)\right| \geqq 2$, and $p_{i} \in X_{a} \cap X_{c}$. Since $\left(X_{a}, \ldots, X_{c}\right)$ is a subsequence of $\left(S_{i}\right)+\mathcal{Y}_{i}+\left(S_{i+1}\right)$, no vertices in $V(P)-\left\{p_{i}\right\}$ are contained in $X_{a} \cap X_{c}$. Moreover, since $X_{b}$ is an element of $\mathcal{Y}_{i}$ for any $b$ with $a<b<c$, it follows from $\left|V\left(P_{i}\right)\right| \geqq 2$ that $\left|X_{b}\right|=3$. Thus, we have that $\left|X_{a} \cap X_{c}\right|=\left|\left\{p_{i}\right\}\right|=1 \leqq\left|X_{b}\right|-2$ for any $b$ with $a<b<c$. Therefore, $\mathcal{X}$ satisfies (e) in Condition 1. It is clear that the width of $\mathcal{X}$ is at most 2 and that $p_{0} \in X_{1}-\bigcup_{1<i \leqq r} X_{i}$ and $p_{l} \in X_{r}-\bigcup_{1 \leqq i<r} X_{i}$. Therefore, $\mathcal{X}$ is a desired proper-path-decomposition.

We describe Algorithm PPD_TREE based on Lemma 3 in Fig. 3. The following corollary is immediate.
Corollary 5: Given a binary tree $T$ and a 2 -spine $P=\left(p_{0}, \ldots, p_{l}\right)$ of $T$ such that $\operatorname{deg}_{T}\left(p_{0}\right)=\operatorname{deg}_{T}\left(p_{l}\right)=$ 1, PPD_TREE outputs in linear time a proper-pathdecomposition $\left(X_{1}, \ldots, X_{r}\right)$ of $T$ with width at most 2 such that $p_{0} \in X_{1}-\bigcup_{1<i \leqq r} X_{i}$ and $p_{l} \in X_{r}-$ $\bigcup_{1 \leqq i<r} X_{i}$.

### 4.2 2-Connected Graphs

In this subsection, we show a necessary and sufficient condition for a 2-connected graph $G$ to have $\operatorname{ppw}(G)=$ 2 , and based on this condition, we give an algorithm for constructing a 2-proper-path-decomposition of $G$. This algorithm is used in the next subsection to construct an algorithm for general graphs.

Theorem 1 is immediate for 2 -connected graphs by
the following lemma.
Lemma 6: For a 2-connected graph $G, p p w(G)=2$ if and only if $G$ is outer planar and has at most two end-regions.
Proof: First, we assume that $p p w(G)=2$. Then none of $M_{1}, K_{4}$, and $K_{2,3}$ which are shown in Fig. 1 is a minor of $G$. It is well-known that the family of outer planar graphs is minor-closed and that $K_{4}$ and $K_{2,3}$ are the minimal forbidden minors for the family of outer planar graphs. Thus $G$ is outer planar. Moreover, $G$ has at most two end-regions since $M_{1}$ is not a minor of $G$.

Next, we assume that $G$ is outer planar and has at most two end-regions. Let $e_{s}$ and $e_{t}$ be any edges in $G$ satisfying the following condition:

Condition 3: $e_{s}$ and $e_{t}$ are outer edges contained in distinct end-regions if $G$ has two end-regions.
It suffices to show the following claim.
Claim 7: There
ex-
ists a 2-proper-path-decomposition $\mathcal{X}=\left(X_{1}, \ldots, X_{r}\right)$ of $G$ such that

$$
\begin{align*}
\left|X_{i}\right| & =3(1 \leqq i \leqq r),  \tag{1}\\
e_{s} & \in E\left(G\left[X_{1}\right]\right)-E\left(G\left[\bigcup_{1<i \leqq r} X_{i}\right]\right), \text { and }  \tag{2}\\
e_{t} & \in E\left(G\left[X_{r}\right]\right)-E\left(G\left[\bigcup_{1 \leqq i<r} X_{i}\right]\right) . \tag{3}
\end{align*}
$$

We prove this claim by induction on $|V(G)|$.
If $|V(G)|=3$ then $\mathcal{X}=(V(G))$ is clearly a desired proper-path-decomposition.

We assume that the claim holds for any $G^{\prime}$ with $|V(G)|-1 \geqq 3$ vertices and for any pair of edges in $G^{\prime}$ satisfying Condition 3 . Since $|V(G)| \geqq 4$, there exists a degree 2 vertex $s$ incident to $e_{s}$ but not to $e_{t}$. Suppose that $e_{s}=(s, y)$ and $N_{G}(s)-\{y\}=\{x\}$. Let $G^{\prime}$ be the graph obtained by contracting the edge $(s, x)$. Since $s$ is identified with $x$, we denote the resulting vertex of $G^{\prime}$ by $x . G^{\prime}$ is clearly an outer planar graph with at most two end-regions. By the definitions of $s, x$, and $y$, $(x, y)$ and $e_{t}$ are distinct edges in $G^{\prime}$ satisfying Condition 3. Therefore, by induction hypothesis, there exists a 2-proper-path-decomposition $\mathcal{Y}=\left(Y_{1}, \ldots, Y_{l}\right)$ of $G^{\prime}$ such that

$$
\begin{align*}
\left|Y_{i}\right| & =3(1 \leqq i \leqq l),  \tag{4}\\
(x, y) & \in E\left(G^{\prime}\left[Y_{1}\right]\right)-E\left(G^{\prime}\left[\bigcup_{1<i \leqq l} Y_{i}\right]\right), \text { and }  \tag{5}\\
e_{t} & \in E\left(G^{\prime}\left[Y_{l}\right]\right)-E\left(G^{\prime}\left[\bigcup_{1 \leqq i<l} Y_{i}\right]\right) . \tag{6}
\end{align*}
$$

We show that $\mathcal{X}=(\{s, x, y\})+\mathcal{Y}$ is a desired 2-proper-path-decomposition of $G$.

We first show that $\mathcal{X}$ satisfies (1), (2), and (3). It follows from (4) and the definition of $\mathcal{X}$ that $\mathcal{X}$ satisfies (1). Since

$$
\begin{equation*}
s \notin Y_{i}(1 \leqq i \leqq l), \tag{7}
\end{equation*}
$$

we have that

$$
\begin{equation*}
e_{s} \in E(G[\{s, x, y\}])-E\left(G\left[\bigcup_{1 \leqq i \leqq l} Y_{i}\right]\right) \tag{8}
\end{equation*}
$$

It follows from (6) and (8) that $\mathcal{X}$ satisfies (2) and (3).
We next show that $\mathcal{X}$ is a 2 -proper-pathdecomposition of $G . \mathcal{X}$ clearly satisfies (a), (b), and (c) in Condition 1. Since $\mathcal{Y}$ is a proper-path-decomposition of $G^{\prime}$ and $\left|Y_{i}\right|=3$ for all $i$ with $1 \leqq i \leqq l$, it follows that

$$
\begin{align*}
& Y_{a} \cap Y_{c} \subseteq Y_{b}(1 \leqq a \leqq b \leqq c \leqq l)  \tag{9}\\
&\left|Y_{a} \cap Y_{c}\right| \leqq\left|Y_{b}\right|-2(1 \leqq a<b<c \leqq l) .
\end{align*}
$$

Thus, to show that $\mathcal{X}$ satisfies (d) and (e) in Condition 1, it suffices to prove that $\{s, x, y\} \cap Y_{c} \subseteq Y_{b}$ and $\left|\{s, x, y\} \cap Y_{c}\right| \leqq\left|Y_{b}\right|-2$ for $1 \leqq b<c \leqq l$. It follows from (5) that

$$
\begin{align*}
& \{x, y\} \subseteq Y_{1},  \tag{10}\\
& \{x, y\} \nsubseteq \bigcup_{1<i \leqq l} Y_{i} . \tag{11}
\end{align*}
$$

It follows from (7), (9), and (10) that $\{s, x, y\} \cap Y_{c}=$ $\{x, y\} \cap Y_{c} \subseteq Y_{1} \cap Y_{c} \subseteq Y_{b}$ for $1 \leqq b<c \leqq l$. It follows from (7) and (11) that $\left|\{s, x, y\} \cap Y_{c}\right| \leqq 1$ for $1<c \leqq l$. Thus we have that $\left|\{s, x, y\} \cap Y_{c}\right| \leqq\left|Y_{b}\right|-2$ for $1 \leqq b<c \leqq l$ by (4).

Therefore,
is a desired 2-proper-path-decomposition of $G$, and we conclude that the lemma holds.

We describe in Fig. 4 Algorithm PPD_2CG based on Lemma 6.
Corollary 8: Given a 2-connected outer planar graph $G$ with at most two end-regions and any edges $e_{s}$ and $e_{t}$ in $G$ satisfying Condition 3, PPD_2CG outputs in linear time a 2 -proper-path-decomposition $\left(X_{1}, \ldots, X_{r}\right)$ of $G$ satisfying (1), (2), and (3).
Proof: The correctness of PPD_2CG is immediate from the proof of Lemma 6. PPD_2CG involves $|V(G)|$ recursive calls each of which consists of constant time operations. Therefore, PPD_2CG can be executed in linear time.

### 4.3 General Graphs

In this subsection, we prove Theorem 1 and describe our algorithm for general graphs. The following lemma will be used extensively throughout this subsection.

Procedure PPD_2CG ( $G, e_{s}, e_{t}$ )
Input: a 2-connected outer planar graph $G$ with at most two end-regions; edges $e_{s}$ and $e_{t}$ satisfying Condition 3 ;
Output: a 2-proper-path-decomposition $\left(X_{1}, \ldots, X_{r}\right)$ of $G$ satisfying (1), (2), and (3);
if $|V(G)|=3$ then return $(V(G))$;
let $s$ be a vertex such that $\operatorname{deg}_{G}(s)=2, e_{s} \in \Gamma(s)$, and $e_{t} \notin \Gamma(s) ;$
let $\{x, y\}:=N_{G}(s)$ such that $(s, y)=e_{s}$;
let $G^{\prime}$ be the graph obtained from $G$ by contracting $(s, x)$;
$\operatorname{return}(\{s, x, y\})+$ PPD_2CG $\left(G^{\prime},(x, y), e_{t}\right) ;$
End

Fig. 4 Algorithm for constructing a 2-proper-pathdecomposition of a 2 -connected graph.

Lemma 9: Let $\mathcal{X}=\left(X_{1}, \ldots, X_{r}\right)$ be a 2-proper-pathdecomposition of a graph $G$ with $p p w(G)=2$. For a path $P$ connecting a vertex $s \in X_{1}$ and a vertex $t \in X_{r}$, every connected component of $G-V(P)$ is a path.
Proof: Suppose that $\mathcal{Y}=\left(Y_{1}, \ldots, Y_{r}\right)$ is $\mathcal{X} \cap(V(G)-$ $V(P))$. It suffices to show that the sequence $\mathcal{Y}^{\prime}$ obtained from $\mathcal{Y}$ by deleting redundant elements is a 1 -proper-path-decomposition of $G-V(P)$. $\mathcal{Y}$ clearly satisfies (b), (c), and (d) in Condition 1 for $G-V(P)$. Thus, $\mathcal{Y}^{\prime}$ satisfies (a), (b), (c), and (d) in Condition 1 for $G-V(P)$. To show that $\mathcal{Y}^{\prime}$ satisfies (e) in Condition 1, it suffices to prove that both of the following statements holds: (i) $\left|Y_{i}\right| \leqq 2$ for any $1 \leqq i \leqq r$; (ii) $Y_{a}=Y_{c}$ or $\left|Y_{a} \cap Y_{c}\right|=0$ for all $a$ and $c$ with $1<a+1 \leqq c-1<r$. Every $X_{i}(1 \leqq i \leqq r)$ contains a vertex of $P$ since end-vertices $s$ and $t$ of $P$ are contained in $X_{1}$ and $X_{t}$, respectively, and $\mathcal{X}$ satisfies (c) and (d) in Condition 1. Since the width of $\mathcal{X}$ is 2 , we have that $\left|Y_{i}\right| \leqq 2$, i.e. (i) holds.

Since $\mathcal{X}$ satisfies (e) in Condition 1, we have that

$$
\begin{equation*}
\left|X_{a} \cap X_{c}\right| \leqq\left|X_{b}\right|-2 \leqq 3-2=1 \tag{12}
\end{equation*}
$$

for any $a, b$, and $c$ with $1 \leqq a<b<c \leqq r$. For $a, b$, and $c$ with $1 \leqq a<b<c \leqq r$, let $p_{a} \in X_{a} \cap V(P)$, $p_{b} \in X_{b} \cap V(P)$, and $p_{c} \in X_{c} \cap V(P)$.

Case $1 p_{a}=p_{c}$. It follows from (12) that $\left|X_{a} \cap X_{c}\right|=$ 1. Thus, we have $\left|Y_{a} \cap Y_{c}\right|=0$.

Case $2 p_{a} \neq p_{c}$. It suffices to show that, if $\left|Y_{a} \cap Y_{c}\right|=1$ then $Y_{a}=Y_{c}$. We assume that $\left|Y_{a} \cap Y_{c}\right|=1$, and show that $Y_{a}=Y_{c}$. Let $v \in Y_{a} \cap Y_{c}$. It follows from (d) in Condition 1 that $v \in Y_{b} \subset X_{b}$. Now we show that $X_{b}-(V(P) \cup\{v\})=\emptyset$. We prove this by contradiction. Assume that $X_{b}-(V(P) \cup\{v\}) \neq \emptyset$. Since $\left|X_{b}\right| \leqq 3$, it follows from assumption that $X_{b} \cap V(P)=\left\{p_{b}\right\}$. Since $P$ connects $s \in X_{1}$ and $t \in X_{r}$, it follows from $1<b<r$ that $p_{b} \in X_{b-1} \cap X_{b+1}$. Moreover, since $v \in Y_{a} \cap Y_{c}$ and $\mathcal{X}$ satisfies (d) in Condition 1, we have that $v \in X_{b-1} \cap X_{b+1}$. Thus, we
have that $\left|X_{b-1} \cap X_{b+1}\right| \geqq\left|\left\{p_{b}, v\right\}\right|=2$, contradicting (12). Therefore, it follows that $X_{b}-(V(P) \cup\{v\})=\emptyset$. Since this holds for any $b$ with $a<b<c$, we have $Y_{a}=Y_{a+1}=\cdots=Y_{c}=\{v\}$.
Therefore, (ii) holds.
In what follows, $G$ is a graph with $\Delta(G)=3$. Let $\mathcal{H}, \mathcal{T}$, and $\mathcal{P}$ be the sets of 2 -connected components, tree components, and path components of $G$, respectively, and $\mathcal{D}=\mathcal{H} \cup \mathcal{T} \cup \mathcal{P}$.

## Proof of Necessity for Theorem 1

We first show the necessity. Assume that $\operatorname{ppw}(G)=2$. Since the theorem is proved for the case of $|\mathcal{D}|=1$ in Sect. 4.1 and 4.2 , we assume that $|\mathcal{D}| \geqq 2$. It follows from assumption that $|V(G)| \geqq 4$. There exists a 2-proper-path-decomposition $\mathcal{X}=\left(X_{1}, \ldots, X_{r}\right)$ of $G$. Since $\mathcal{X}$ satisfies (a) in Condition 1 and $|V(G)| \geqq 4$, there exist $s \in X_{1}-X_{2}$ and $t \in X_{r}-X_{r-1}$. We define that $S$ is a path connecting $s$ and $t$.
Claim 10: For $D \in \mathcal{D}, D \cap S$ is connected if $D \cap S$ has a vertex.
Proof: By the definitions of 2-connected components, tree components, and path components, every path in $G$ connecting vertices of $D$ is a subgraph of $D$. Thus, the claim holds.

Let $C_{1}, C_{2}, \ldots, C_{m}$ be components in $\mathcal{D}$ containing an edge of $S$. By Claim 10, $C_{i} \cap S$ is a subpath of $S(1 \leqq i \leqq m)$. Moreover, $C_{i} \cap S$ and $C_{j} \cap S$ are internally vertex-disjoint since $C_{i}$ and $C_{j}$ share at most one connection point for $1 \leqq i<j \leqq m$. Thus we may assume without loss of generality that $C_{i} \cap S$ and $C_{i+1} \cap S$ share a connection point $a_{i}$ for $1 \leqq i<m$. Let $a_{0}=s$ and $a_{m}=t$. Notice that $a_{i-1}$ and $a_{i}$ are end-vertices of $C_{i} \cap S$ for $1 \leqq i \leqq m$. Moreover, $a_{i-1}$ and $a_{i}$ are distinct vertices since $C_{i} \cap S$ has at least two vertices for $1 \leqq i \leqq m$. This means that $a_{0}, a_{1}, \ldots, a_{m}$ are distinct vertices of $G$. We define that $\mathcal{C}=\left(C_{1}, C_{2}, \ldots, C_{m}\right)$ and $\mathcal{A}=\left(a_{0}, a_{1}, \ldots, a_{m}\right)$. We show that $\mathcal{C}$ and $\mathcal{A}$ satisfies Condition 2.
$\mathcal{C}$ and $\mathcal{A}$ clearly satisfies (a) in Condition 2 by definition. The following claim shows that $\mathcal{C}$ and $\mathcal{A}$ satisfies (b) in Condition 2.

Claim 11: $\operatorname{deg}_{G}(s) \leqq 2$ and $\operatorname{deg}_{G}(t) \leqq 2$.
Proof: $\left|X_{1}\right| \leqq 3$ and $\left|X_{r}\right| \leqq 3$ since the width of $\mathcal{X}$ is 2. Thus, we have $\operatorname{deg}_{G}(s) \leqq 2$ and $\operatorname{deg}_{G}(t) \leqq 2$ since $s$ is only in $X_{1}$ and $t$ is only in $X_{r}$.

The following claim shows that $\mathcal{C}$ and $\mathcal{A}$ satisfy (c) in Condition 2.
Claim 12: If $C_{i} \in \mathcal{T}(1 \leqq i \leqq m)$, then the path in $C_{i}$ connecting $a_{i-1}$ and $a_{i}$ is a 2 -spine of $C_{i}$.
Proof: Let $S^{\prime}$ be the path in $C_{i}$ connecting $a_{i-1}$ and $a_{i}$. By Lemma 9 , every connected component of $G-V(S)$ is a path. Since $S^{\prime}$ is a subpath of $S$, every connected component of $C_{i}-V\left(S^{\prime}\right)$ is a path. This means that $S^{\prime}$ is a 2 -spine of $C_{i}$.

The following claim shows that $\mathcal{C}$ and $\mathcal{A}$ satisfy (d) in Condition 2. Let $P_{i}^{s}=\left(s, \ldots, a_{i}\right)$ and $P_{i}^{t}=$ $\left(a_{i}, \ldots, t\right)$ be the subpaths of $S$ for $0 \leqq i \leqq m$.
Claim 13: If $C_{i} \in \mathcal{H}(1 \leqq i \leqq m)$, then $C_{i}$ is an outer planar graph with at most two end-regions. Moreover, each end-region contains $a_{i-1}$ or $a_{i}$.
Proof: Suppose that $C_{i} \in \mathcal{H}(1 \leqq i \leqq m)$. Since $\operatorname{ppw}(G)=2$, we have that $\operatorname{ppw}\left(C_{i}\right)=2$. Thus, $C_{i}$ is an outer planar graph with at most two end-regions from Lemma 6. It remains to show that each end-region of $C_{i}$ contains $a_{i-1}$ or $a_{i}$. If $C_{i}$ has an end-region $Z$ which contains neither $a_{i-1}$ nor $a_{i}$, then there exists a path $\bar{P}$ in $C_{i}$ which connects $a_{i-1}$ and $a_{i}$ and contains no vertices in $Z . \quad S^{\prime}=P_{i-1}^{s} \cup \bar{P} \cup P_{i}^{t}$ is clearly a path connecting $s$ and $t$. Since $S^{\prime}$ and $Z$ are vertex-disjoint, $G-V\left(S^{\prime}\right)$ contains a cycle as a subgraph. However, this contradicts Lemma 9. Thus, each end-region of $C_{i}$ contains $a_{i-1}$ or $a_{i}$.

The following claim shows that $\mathcal{C}$ and $\mathcal{A}$ satisfy (e) in Condition 2. Let $\mathcal{D}^{\prime}=\mathcal{D}-\left\{C_{i} \mid 1 \leqq i \leqq m\right\}$.
Claim 14: $\quad \mathcal{D}^{\prime} \subseteq \mathcal{P}$.
Proof: We show that any $D \in \mathcal{H} \cup \mathcal{T}$ is an element of $\mathcal{C}$. By Claim 10 and the definition of $\mathcal{C}$, it suffices to show that $|V(D \cap S)| \geqq 2$. By Lemma $9, D \cap S$ has at least one vertex. Thus it remains to show that $|V(D \cap S)| \neq 1$. We prove this by contradiction. Assume that $V(D \cap S)=\{x\}$.

Case $1 D \in \mathcal{H}$. If $x \in V(S)-\{s, t\}$ then we have $\operatorname{deg}_{G}(x)=\operatorname{deg}_{D}(x)+\operatorname{deg}_{S}(x) \geqq 2+2=4$, which is a contradiction since $\Delta(G)=3$. If $x \in\{s, t\}$ then we have $\operatorname{deg}_{G}(x)=\operatorname{deg}_{D}(x)+\operatorname{deg}_{S}(x) \geqq 2+1=3$, which also contradicts Claim 11.
Case $2 D \in \mathcal{T}$. Since there exists an edge in $\Gamma_{S}(x)$ which is not contained in $D, x$ is a connection point of $G$. Thus, there exists $H \in \mathcal{H}$ containing $x$. Since $H$ is 2-connected and $\Delta(G)=3, x$ is incident to just two edges of $H$ and to exactly one edge of $D$. Thus, it follows from Claim 11 that $x \notin\{s, t\}$ and $S$ has two edges in $\Gamma_{H}(x)$. This means that $H$ is an element of $\mathcal{C}$ and $x \notin\left\{a_{i} \mid 0 \leqq i \leqq m\right\}$. Suppose that $H=C_{i}$ $(1 \leqq i \leqq m)$. Since $C_{i}$ is 2 -connected, there exists a path $\bar{P}$ in $C_{i}$ which connects $a_{i-1}$ and $a_{i}$ and does not contain $x . S^{\prime}=P_{i-1}^{s} \cup \bar{P} \cup P_{i}^{t}$ is a path connecting $s$ and $t$. Since $S^{\prime}$ and $D$ are vertex-disjoint and $D$ has a degree 3 vertex, $G-V\left(S^{\prime}\right)$ has a degree 3 vertex, contradicting Lemma 9.

Thus, we conclude that $|V(D \cap S)| \neq 1$ and the claim holds.

We prove by a sequence of claims that $\mathcal{C}$ and $\mathcal{A}$ satisfy (f) in Condition 2. It is clear that $P \in \mathcal{D}^{\prime}$ has exactly one connection point. We denote the connection point by $c(P)$.
Claim 15: For $P \in \mathcal{D}^{\prime}$, there exists a unique $C_{i} \in \mathcal{H}$ $(1 \leqq i \leqq m)$ such that $c(P) \in V\left(C_{i}\right)$. Moreover, $\left(c(P), a_{i-1}\right) \in E\left(C_{i}\right)$ or $\left(c(P), a_{i}\right) \in E\left(C_{i}\right)$.

Proof: Since $\Delta(G)=3$, it is clear that for $P \in \mathcal{D}^{\prime}$, there exists a unique $C_{i} \in \mathcal{H}(1 \leqq i \leqq m)$ such that $c(P) \in V\left(C_{i}\right)$. We show that $\left(c(P), a_{i-1}\right) \in E\left(C_{i}\right)$ or $\left(c(P), a_{i}\right) \in E\left(C_{i}\right)$. We prove this by contradiction. Assume that $\left(c(P), a_{i-1}\right) \notin E\left(C_{i}\right)$ and $\left(c(P), a_{i}\right) \notin E\left(C_{i}\right)$. $c(P)$ is neither $a_{i-1}$ nor $a_{i}$ from Claim 11 and the assumption that $\Delta(G)=3$. Thus, neither $a_{i-1}$ nor $a_{i}$ is contained in $N_{G}(c(P)) \cup\{c(P)\}$. Since $C_{i}$ is 2-connected outer planar graph with $\Delta(G)=3, c(P)$ is incident to just two outer edges of $C_{i}$ and to exactly one edge of $P$. Thus, there exists a path $\bar{P}$ in $C_{i}$ which connects $a_{i-1}$ and $a_{i}$ and does not contain a vertex incident to the two outer edges. $S^{\prime}=P_{i-1}^{s} \cup \bar{P} \cup P_{i}^{t}$ is a path connecting $s$ and $t$. Since $S^{\prime}$ has no vertex adjacent to $c(P), G-V\left(S^{\prime}\right)$ has $c(P)$ with degree 3 , contradicting Lemma 9.
Claim 16: For distinct $P_{1}, P_{2} \in \mathcal{D}^{\prime}, c\left(P_{1}\right) \neq c\left(P_{2}\right)$.
Proof: Each $c\left(P_{i}\right)(i=1,2)$ is contained in a 2 connected component of $G$ by Claim 15. If $c\left(P_{1}\right)=$ $c\left(P_{2}\right)$ then $\operatorname{deg}_{G}\left(c\left(P_{i}\right)\right) \geqq 4(i=1,2)$, contradicting the assumption that $\Delta(G)=3$.
Claim 17: Suppose that $C_{i} \in \mathcal{H}(1 \leqq i \leqq m)$. If there exist distinct $P_{1}, P_{2} \in \mathcal{D}^{\prime}$ such that both $c\left(P_{1}\right)$ and $c\left(P_{2}\right)$ are adjacent to $a \in\left\{a_{i-1}, a_{i}\right\}$, then $c\left(P_{1}\right)$ or $c\left(P_{2}\right)$ is adjacent to $a^{\prime} \in\left\{a_{i-1}, a_{i}\right\}-\{a\}$.
Proof: We show the claim by contradiction. Assume that there exist distinct $P_{1}, P_{2} \in \mathcal{D}^{\prime}$ such that both $c\left(P_{1}\right)$ and $c\left(P_{2}\right)$ are adjacent to $a \in\left\{a_{i-1}, a_{i}\right\}$ and that neither $c\left(P_{1}\right)$ nor $c\left(P_{2}\right)$ is adjacent to $a^{\prime} \in\left\{a_{i-1}, a_{i}\right\}-$ $\{a\}$. Let $L$ be the subgraph of $G$ induced by all the outer edges of $C_{i}$. Suppose that $N_{L}\left(a^{\prime}\right)=\{u, v\}$. It follows from the assumption and Claims 15 and 16 that $a, a^{\prime}, u, v, c\left(P_{1}\right)$, and $c\left(P_{2}\right)$ are distinct vertices.

If there exists an edge $e \in E(G)-E\left(C_{i}\right)$ incident to $a^{\prime}$, then $M_{3}$ shown in Fig. 1 is a minor of the subgraph $L \cup P_{1} \cup P_{2} \cup G[\{e\}]$ of $G$, i.e. $p p w(G)>2$. This means that $\Gamma_{G}\left(a^{\prime}\right)-E\left(C_{i}\right)=\emptyset$ and that the properpathwidth of the graph $G^{\prime}$ obtained from $G$ by adding an additional vertex $x$ and by joining $a^{\prime}$ and $x$ by an additional edge is more than 2. If $a^{\prime}=a_{j}(1 \leqq j<m)$ then $\Gamma_{G}\left(a^{\prime}\right)-E\left(C_{i}\right) \neq \emptyset$ clearly. Thus we have that $a^{\prime}=a_{0}(=s)$ or $a^{\prime}=a_{m}(=t)$. Let $\mathcal{X}^{\prime}=(\{x, s\})+\mathcal{X}$ if $a^{\prime}=s, \mathcal{X}^{\prime}=\mathcal{X}+(\{t, x\})$ otherwise. It is not difficult to see that $\mathcal{X}^{\prime}$ is a proper-path-decomposition of $G^{\prime}$ and that the width of $\mathcal{X}^{\prime}$ is 2 . This means that $\operatorname{ppw}\left(G^{\prime}\right)=2$, a contradiction.
Claim 18: For $C_{i} \in \mathcal{H}(1 \leqq i \leqq m), \mid\left\{P \in \mathcal{D}^{\prime} \mid\right.$ $\left.c(P) \in V\left(C_{i}\right)\right\} \mid \leqq 2$.
Proof: We show the claim by contradiction. Assume that there exist distinct $P_{1}, P_{2}, P_{3} \in \mathcal{D}^{\prime}$ such that $\left\{c\left(P_{1}\right), c\left(P_{2}\right), c\left(P_{3}\right)\right\} \subseteq V\left(C_{i}\right)$. Let $L$ be the subgraph of $G$ induced by all the outer edges of $C_{i}$. Moreover, let $G^{\prime}$ be the graph obtained from $G$ by adding additional vertices $x$ and $y$ and edges $(x, s)$ and $(y, t)$. Notice that there exist distinct edges $e \in \Gamma_{G^{\prime}}\left(a_{i-1}\right)-E\left(C_{i}\right)$ and $e^{\prime} \in \Gamma_{G^{\prime}}\left(a_{i}\right)-E\left(C_{i}\right)$. As shown in the proof of Claim 15,
$\left\{c\left(P_{1}\right), c\left(P_{2}\right), c\left(P_{3}\right)\right\} \cap\left\{a_{i-1}, a_{i}\right\}=\emptyset$. Thus it follows from Claim 16 that $c\left(P_{1}\right), c\left(P_{2}\right), c\left(P_{3}\right), a_{i-1}$, and $a_{i}$ are distinct vertices. Therefore, $M_{2}$ shown in Fig. 1 is a minor of the subgraph $L \cup P_{1} \cup P_{2} \cup P_{3} \cup G^{\prime}\left[\left\{e, e^{\prime}\right\}\right]$ of $G^{\prime}$, i.e. $\operatorname{ppw}\left(G^{\prime}\right)>2$. However, it is not difficult to see that $\mathcal{X}^{\prime}=(\{x, s\})+\mathcal{X}+(\{t, y\})$ is a proper-pathdecomposition of $G^{\prime}$ and that the width of $\mathcal{X}^{\prime}$ is 2 . Thus we have $\operatorname{ppw}\left(G^{\prime}\right)=2$, a contradiction.
Claim 19: $\mathcal{C}$ and $\mathcal{A}$ satisfy (f) in Condition 2.
Proof: It follows from Claim 15 that there exists a mapping $f$ satisfying the statement ( $*$ ) in Condition 2. By Claims 17 and $18, f$ can easily be reconstructed so that it is a one-to-one mapping satisfying ( $*$ ).

Thus, $\mathcal{C}$ and $\mathcal{A}$ satisfy Condition 2 . Therefore, the proof of necessity for Theorem 1 is completed.

## Proof of Sufficiency for Theorem 1

We next show the sufficiency. Assume that $G$ has a sequence $\mathcal{C}=\left(C_{1}, C_{2}, \ldots, C_{m}\right)$ of components in $\mathcal{D}$ and a sequence $\mathcal{A}=\left(a_{0}, a_{1}, \ldots, a_{m}\right)$ of vertices of $G$ such that Condition 2 is satisfied. If $C_{1} \in \mathcal{T}$ and $\operatorname{deg}_{G}\left(a_{0}\right)=2$ then we can easily find a vertex $a_{0}^{\prime} \in V\left(C_{1}\right)$ such that $\operatorname{deg}_{G}\left(a_{0}^{\prime}\right)=1$ and that the path connecting $a_{0}^{\prime}$ and $a_{1}$ is a 2 -spine of $C_{1}$. Moreover, $\mathcal{C}$ and the sequence $\left(a_{0}^{\prime}, a_{1}, \ldots, a_{m}\right)$ satisfy Condition 2 . Thus, we assume without loss of generality that, if $C_{1} \in \mathcal{T}$ then $\operatorname{deg}_{G}\left(a_{0}\right)=1$. Similarly, we assume without loss of generality that, if $C_{m} \in \mathcal{T}$ then $\operatorname{deg}_{G}\left(a_{m}\right)=1$.

For $C_{i} \in \mathcal{H}(1 \leqq i \leqq m)$, we define that $e_{i}^{0}$ and $e_{i}^{1}$ are distinct edges of $C_{i}$ incident to $a_{i}$ and $a_{i-1}$, respectively, such that if there exists $P \in \mathcal{D}^{\prime}$ with $f(P)=(i, j)$ then $e_{i}^{j}=\left(a_{i-j}, c(P)\right)(j=0,1)$. The following claim shows that $e_{i}^{0}$ and $e_{i}^{1}$ satisfy Condition 3 for $C_{i} \in \mathcal{H}$.
Claim 20: For $C_{i} \in \mathcal{H}, e_{i}^{0}$ and $e_{i}^{1}$ are outer edges of $C_{i}$. Moreover, they are contained in distinct endregions if $C_{i}$ has two end-regions.
Proof: The claim is immediate if $C_{i}$ has a single endregion. Thus, we assume $C_{i}$ has two end-regions. Since (b) in Condition 2 is satisfied and $\Delta(G)=3$, we have that $\operatorname{deg}_{C_{i}}\left(a_{i-1}\right)=\operatorname{deg}_{C_{i}}\left(a_{i}\right)=2$. Thus, two edges incident to $a \in\left\{a_{i-1}, a_{i}\right\}$ are outer edges contained in a same region. Moreover, since (d) in Condition 2 is satisfied, $a_{i-1}$ and $a_{i}$ are contained in distinct end-regions. Therefore, $\Gamma_{C_{i}}\left(a_{i-1}\right)$ and $\Gamma_{C_{i}}\left(a_{i}\right)$ are subsets of edges of distinct end-regions. Since $e_{i}^{j} \in \Gamma_{C_{i}}\left(a_{i-j}\right)(j=0,1)$, the claim holds.

We show that the sequence $\mathcal{X}=\left(X_{1}, \ldots, X_{r}\right)$ of subsets of $V(G)$ defined as follows is a 2-proper-pathdecomposition of $G$.

$$
\mathcal{X}=\sum_{1 \leqq i \leqq m} \mathcal{L}^{i}+\mathcal{Y}^{i}+\mathcal{R}^{i}, \text { where for } 1 \leqq i \leqq m
$$

$$
\begin{aligned}
& \mathcal{Y}^{i}= \begin{cases}\operatorname{PPD} \_ \text {TREE }\left(C_{i}, \text { path }\left(a_{i-1}, \ldots, a_{i}\right)\right) \\
& \text { if } C_{i} \in \mathcal{T} \cup \mathcal{P} \\
\operatorname{PPD\_ 2CG}\left(C_{i}, e_{i}^{1}, e_{i}^{0}\right) & \text { if } C_{i} \in \mathcal{H}\end{cases} \\
& \mathcal{L}^{i}=\left\{\begin{array}{c}
\operatorname{PPD} \_\operatorname{PATH}\left(P=\left(p_{0}, \ldots, c(P)\right)\right) \cup\left\{a_{i-1}\right\} \\
\text { if } \exists P \in \mathcal{D}^{\prime} \text { with } f(P)=(i, 1) \\
\text { nul } \\
\text { otherwise }
\end{array}\right. \\
& \mathcal{R}^{i}=\left\{\begin{array}{l}
\text { PPD_PATH }\left(P=\left(c(P), \ldots, p_{l}\right)\right) \cup\left\{a_{i}\right\} \\
\text { if } \exists P \in \mathcal{D}^{\prime} \text { with } f(P)=(i, 0) \\
n u l \\
\text { otherwise }
\end{array}\right.
\end{aligned}
$$

$\mathcal{X}$ satisfies (a), (b), and (c) in Condition 1 by definition. Moreover, every element of $\mathcal{X}$ contains at most three vertices of $G$. Thus, it suffices to show that $\mathcal{X}$ satisfies (d) and (e) in Condition 1. By the definition of PPD_PATH and Corollaries 5 and 8, we can observe the following claim.

## Claim 21:

1. For $1 \leqq i \leqq m, v \in V\left(C_{i}\right)-\left(\left\{a_{i-1}, a_{i}\right\} \cup\{c(P) \mid\right.$ $\left.\left.P \in \mathcal{D}^{\prime}\right\}\right)$ appears in consecutive elements of $\mathcal{Y}^{i}$.
2. For $P \in \mathcal{D}^{\prime}, v \in V(P)-\{c(P)\}$ appears in at most two consecutive elements of $\mathcal{X}$.
3. For $0 \leqq i \leqq m, a_{i}$ appears consecutive elements of $\mathcal{Y}^{i}+\mathcal{R}^{i}+\mathcal{L}^{i+1}+\mathcal{Y}^{i+1}$, where $\mathcal{Y}^{0}=\mathcal{R}^{0}=\mathcal{Y}^{m+1}=$ $\mathcal{L}^{m+1}=$ nul.
4. For $P \in \mathcal{D}^{\prime}$ with $f(P)=(i, 1), c(P)$ appears in the tail of $\mathcal{L}^{i}$ and in consecutive elements of $\mathcal{Y}^{i}$ including its head.
5. For $P \in \mathcal{D}^{\prime}$ with $f(P)=(i, 0), c(P)$ appears in the head of $\mathcal{R}^{i}$ and in consecutive elements of $\mathcal{Y}^{i}$ including its tail.

It follows from Claim 21 that every vertex in $G$ appears in consecutive elements of $\mathcal{X}$. Thus, $\mathcal{X}$ satisfies (d) in Condition 1.

It remains to show that $\mathcal{X}$ satisfies (e) in Condition 1. If $X_{a} \cap X_{c}=\emptyset$ for all $a$ and $c$ with $1<a+1 \leqq$ $c-1<r$, then this is immediate. Thus, we assume that there exist $a$ and $c$ with $1<a+1 \leqq c-1<r$ such that $X_{a} \cap X_{c} \neq \emptyset$. For $1 \leqq i \leqq m, \mathcal{Y}^{i}$ is a proper-path-decomposition of $C_{i}$. Thus, we have that $\left|X_{a} \cap X_{c}\right| \leqq\left|X_{b}\right|-2$ for any $b$ with $a<b<c$ if there exists $i$ with $1 \leqq i \leqq m$ such that both $X_{a}$ and $X_{c}$ are elements of $\mathcal{Y}^{i}$. Therefore, we assume that there exists no $i$ with $1 \leqq i \leqq m$ such that both $X_{a}$ and $X_{c}$ are elements of $\mathcal{Y}^{i}$. It follows from assumption and Claim 21 that $X_{a} \cap X_{c}$ contains at most one vertex in $\mathcal{A}$ and at most one vertex in $\left\{c(P) \mid P \in \mathcal{D}^{\prime}\right\}$.
Claim 22: $\left|X_{a} \cap X_{c}\right|=1$.
Proof: It suffices to show that both $a_{i}(0 \leqq i \leqq m)$ and $c(P)$ are not contained in $X_{a} \cap X_{c}$. We prove this by contradiction. Assume that there exist $i(0 \leqq i \leqq m)$ and $P \in \mathcal{D}^{\prime}$ such that $\left\{a_{i}, c(P)\right\} \subseteq X_{a} \cap X_{c}$. By

Claim 21 and the assumption that no $\mathcal{Y}^{i}(1 \leqq i \leqq m)$ contains both $X_{a}$ and $X_{c}$, we have that $f(P)=(i, 0)$ or $f(P)=(i+1,1)$. We may assume without loss of generality that $f(P)=(i, 0)$. Then, both $X_{a}$ and $X_{c}$ are elements of $\mathcal{Y}^{i}+\left(\right.$ the head of $\left.\mathcal{R}^{i}\right)$. Suppose that $\mathcal{Y}^{i}=\left(Y_{1}^{i}, \ldots, Y_{r}^{i}\right)$. Since $c-a \geqq 2$, we have that $X_{a} \neq Y_{r}^{i}$. Thus, there exists $j$ with $1 \leqq j<r$ such that $\left\{a_{i}, c(P)\right\} \subseteq X_{a}=Y_{j}^{i}$. However, this is impossible since $\left(a_{i}, c(P)\right)=e_{i}^{0} \in E\left(G\left[Y_{r}^{i}\right]\right)-E\left(G\left[\bigcup_{1 \leqq j<r} Y_{j}^{i}\right]\right)$ by Corollary 8.
Claim 23: $\left|X_{b}\right|=3$ for any $b$ with $a<b<c$.
Proof: Let $b$ be any integer such that $a<b<c$. If there exists $i(1 \leqq i \leqq m)$ such that $X_{b}$ is an element of $\mathcal{Y}^{i}$ and that $C_{i} \in \mathcal{H}$, then $\left|X_{b}\right|=3$ by Corollary 8. If there exists $i(1 \leqq i \leqq m)$ such that $X_{b}$ is an element of $\mathcal{L}^{i}$ or $\mathcal{R}^{i}$, then $\left|X_{b}\right|=3$ by the definition of PPD_PATH and by the fact that $|V(P)| \geqq 2$ for any $P \in \mathcal{D}^{\prime}$. Thus, it suffices to show that $X_{b}$ is not an element of $\mathcal{Y}^{i}$ such that $C_{i} \in \mathcal{T} \cup \mathcal{P}$. We prove this by contradiction. Assume that $X_{b}$ is an element of $\mathcal{Y}^{i}$ $(1 \leqq i \leqq m)$ such that $C_{i} \in \mathcal{T} \cup \mathcal{P}$. It follows from the assumption and Claim 22 that either $X_{a} \cap X_{c}=\left\{a_{i-1}\right\}$ or $X_{a} \cap X_{c}=\left\{a_{i}\right\}$. We assume without loss of generality that $X_{a} \cap X_{c}=\left\{a_{i}\right\}$. Since $X_{b}$ is an element of $\mathcal{Y}^{i}, X_{a}$ is an element of $\mathcal{Y}^{i}$ except the tail. This means that $a_{i}$ is contained in an element of $\mathcal{Y}^{i}$ except the tail. However, this is impossible since $a_{i}$ is an end-vertex of 2-spine of $C_{i}$ and $a_{i}$ appears only in the tail of $\mathcal{Y}^{i}$ by Corollary 5 .
It follows from Claims 22 and 23 that $\left|X_{a} \cap X_{c}\right|-\left|X_{b}\right|=$ $3-2=1$ for $a<b<c$. Thus, $\mathcal{X}$ satisfies (e) in Condition 1 .

Therefore, $\mathcal{X}$ is a 2 -proper-path-decomposition of $G$ and the proof of sufficiency for Theorem 1 is completed.

We describe in Fig. 5 Algorithm PPD_GENERAL based on Theorem 1. It is well-known that we can find all blocks of a graph in linear time. Moreover, we can determine if a given graph is outer planar in linear time [4]. To find $a_{0}$ and $a_{m}$ in step 3, we need an algorithm to find a 2 -spine of a binary tree, which has not been described yet. Although the details are not mentioned here, this can be done in linear time by using a simple postorder searching and the algorithm in [8], which outputs, for a rooted binary tree, the proper-pathwidth of every subtree rooted at a vertex. The other operations in PPD_GENERAL clearly executed in linear time.

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## Procedure PPD_GENERAL ( $G$ )

Input: a connected graph $G$ with $\Delta(G) \leqq 3$;
Output: a 2-proper-path-decomposition of $G$;

1. let $\mathcal{H}, \mathcal{T}$, and $\mathcal{P}$ be the sets of 2 -connected components, tree components, and path components of $G$, respectively;
2. $\mathcal{D}:=\mathcal{H} \cup \mathcal{T} \cup \mathcal{P}$;
3. find a sequence $\mathcal{C}=\left(C_{1}, C_{2}, \ldots, C_{m}\right)$ of components in $\mathcal{D}$ and a sequence $\mathcal{A}=\left(a_{0}, a_{1}, \ldots, a_{m}\right)$ of vertices of $G$ such that Condition 2 and the following conditions are satisfied:

$$
\begin{aligned}
& \operatorname{deg}_{G}\left(a_{0}\right)=1 \text { if } C_{1} \in \mathcal{T} \\
& \operatorname{deg}_{G}\left(a_{m}\right)=1 \text { if } C_{m} \in \mathcal{T}
\end{aligned}
$$

4. if $\mathcal{C}$ and $\mathcal{A}$ do not exist then reject ;
5. $\mathcal{D}^{\prime}:=\mathcal{D}-\left\{C_{i} \mid 1 \leqq i \leqq m\right\}$;
6. for each $C_{i} \in H$ do
a. find distinct edges $e_{i}^{0} \in \Gamma_{C_{i}}\left(a_{i}\right)$ and $e_{i}^{1} \in \Gamma_{C_{i}}\left(a_{i-1}\right)$ such that, if there exists $P \in \mathcal{D}^{\prime}$ with $f(P)=(i, j)$ then $e_{i}^{j}=\left(a_{i-j}, c(P)\right)(j=0,1)$;
endfor ;
7. for $i=1$ to $m$ do
a. if $C_{i} \in \mathcal{T} \cup \mathcal{P}$ then
$\mathcal{Y}^{i}:=$ PPD_TREE $\left(C_{i}\right.$, path $\left.\left(a_{i-1}, \ldots, a_{i}\right)\right)$;
else $\mathcal{Y}^{i}:=$ PPD_2CG $\left(C_{i}, e_{i}^{1}, e_{i}^{0}\right)$;
b. if $\exists P \in \mathcal{D}^{\prime}$ with $f(P)=(i, 1)$ then
$\mathcal{L}^{i}:=\operatorname{PPD} \_\operatorname{PATH}\left(P=\left(p_{0}, \ldots, c(P)\right)\right) \cup\left\{a_{i-1}\right\} ;$
else $\mathcal{L}^{i}:=n u l ;$
c. if $\exists P \in \mathcal{D}^{\prime}$ with $f(P)=(i, 0)$ then
$\mathcal{R}^{i}:=$ PPD_PATH $\left(P=\left(c(P), \ldots, p_{l}\right)\right) \cup\left\{a_{i}\right\}$;
else $\mathcal{R}^{i}:=n u l ;$
endfor ;
8. return $\sum_{1 \leqq i \leqq m} \mathcal{L}^{i}+\mathcal{Y}^{i}+\mathcal{R}^{i} ;$

End
Fig. 5 Algorithm for constructing a 2-proper-pathdecomposition of a general graph.

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