A Linear Time Algorithm for Constructing Proper-Path-Decomposition of Width Two

メタデータ 言語: eng 出版者: 公開日: 2017-10-03 キーワード (Ja): キーワード (En): 作成者: メールアドレス: 所属: URL http://hdl.handle.net/2297/3541 PAPER Special Section on Discrete Mathematics and Its Applications

A Linear Time Algorithm for Constructing Proper-Path-Decomposition of Width Two

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SUMMARY The problem of constructing the proper-path-decomposition of width at most 2 has an application to the efficient graph layout into ladders. In this paper, we give a linear time algorithm which, for a given graph with maximum vertex degree at most 3, determines whether the proper-pathwidth of the graph is at most 2, and if so, constructs a proper-path-decomposition of width at most 2.

 $key\ words:\ proper-path-decomposition,\ proper-pathwidth,\ path-width,\ graph\ layout$

1. Introduction

The pathwidth of a graph G is the minimum value of ksuch that G can be obtained from a sequence of graphs H_1, H_2, \ldots, H_r each of which has at most k+1 vertices, by identifying some vertices of H_i pairwise with some of $H_{i+1}(1 \leq i < r)$ [5]. The sequence H_1, H_2, \ldots, H_r is called a path-decomposition of G with width k. The proper-pathwidth is introduced in [6] as a variant of the pathwidth. The (proper-)pathwidth is closely related to other graph parameters such as cutwidth, topological bandwidth, and search numbers. It is NP-complete to decide, given a graph G and an integer k, whether the (proper-)pathwidth of G is at most k, while the problem is in P if k is a fixed integer. It is shown in [2] that if the pathwidth of a graph G is bounded by a fixed integer k then a path-decomposition of G with width kcan be constructed in polynomial time. On the other hand, no polynomial time algorithm is known for the problem of constructing a proper-path-decomposition of width k for a graph with proper-pathwidth bounded by a fixed integer $k \geq 2$.

The graphs which can be laid out into ladders are characterized in terms of the proper-pathwidth of graphs [3]. It is known that finding a proper-path-decomposition of width 2 for a graph with maximum vertex degree 3 and proper-pathwidth 2 is crucial to lay out such a graph into the ladder [3].

The purpose of this paper is to give a linear time algorithm for constructing a proper-path-decomposition of width 2 for a graph with maximum vertex degree 3 and proper-pathwidth 2.

Manuscript received September 16, 1997.

Manuscript revised January 6, 1998.

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It is shown in [1] that if the treewidth of a graph G is bounded by a fixed integer k then a treedecomposition of G with width k can be constructed in linear time and, by using this fact and the result of [2], a path-decomposition of G with minimum width can also be constructed in linear time. However, this result cannot be generalized immediately to our problem of constructing proper-path-decompositions of minimum width since there exist graphs with the proper-pathwidth more than the pathwidth because of an additional condition ((e) in Condition 1 given in Sect. 2) which is introduced to define the proper-path-decomposition.

The rest of the paper is organized as follows. Some definitions are given in Sect. 2. In Sect. 3, we give a characterization of graphs with maximum vertex degree 3 and proper-pathwidth 2. We give in Sect. 4 the proof of the characterization and an algorithm for constructing a proper-path-decomposition of width 2.

2. Preliminaries

Let G be a graph and let V(G) and E(G) denote the vertex set and edge set of G, respectively. $\Gamma_G(v)$ is the set of edges incident to a vertex v in G. $|\Gamma_G(v)|$ is called the *degree* of v and denoted by $\deg_G(v)$. Let $\Delta(G) = \max\{\deg_G(v) \mid v \in V(G)\}.$ $N_G(v)$ is the set of vertices adjacent to a vertex v in G. For $U \subseteq V(G)$, let G[U] be the subgraph of G induced by U, and let G - U denote G[V(G) - U]. Similarly, for $S \subseteq E(G)$, let G[S] be the subgraph of G induced by S, and let G-S denote the graph obtained from G by deleting S. For graphs G and H, $G \cup H$ is the graph with vertex set $V(G) \cup V(H)$ and edge set $E(G) \cup E(H)$, and $G \cap H$ is the graph with vertex set $V(G) \cap V(H)$ and edge set $E(G) \cap E(H)$. Although a path is a graph, we often denote a path by a sequence of vertices in which consecutive two vertices are adjacent in the path.

A vertex v of G is a cut vertex if E(G) can be partitioned into two nonempty subsets E_1 and E_2 such that $G[E_1]$ and $G[E_2]$ have just the vertex v in common. A connected graph that has no cut vertices is called a block. Every block with at least three vertices is 2-connected. A block of a graph is a subgraph that is a block and is maximal with respect to this property.

A graph is *outer planar* if it has a planar drawing

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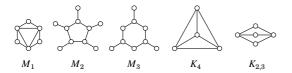


Fig. 1 Minimal forbidden minors for \mathcal{P}_2 .

in which the outer region includes all of its vertices. An edge is *outer* if it is included in the outer region, and is *inner* otherwise. A cycle C of an outer planar graph G is an *end-region* of G if C = G[V(C)] and C has at most one inner edge. Any 2-connected outer planar graph has at least one end-region, and it has at least two end-regions if it has an inner edge.

For a graph G, a sequence $\mathcal{X} = (X_1, \ldots, X_r)$ of subsets of V(G) is called a *proper-path-decomposition* of G if \mathcal{X} satisfies the following conditions.

Condition 1:

- (a) $X_i \not\subseteq X_j \ (i \neq j);$
- (b) $\bigcup_{1 \le i \le r} X_i = V(G);$
- (c) for any $(u, v) \in E(G)$, there exists an i such that $u, v \in X_i$;
- (d) for all a, b, and c with $1 \le a \le b \le c \le r$, $X_a \cap X_c \subseteq X_b$;
- (e) for all a, b, and c with $1 \le a < b < c \le r$, $|X_a \cap X_c| \le |X_b| 2$ if $|X_b| \ge 2$.

The width of \mathcal{X} is $\max_{1 \leq i \leq r} |X_i| - 1$. The properpathwidth of G is the minimum width over all properpath-decompositions of G, and denoted by ppw(G). A proper-path-decomposition is said to be optimal if it has width of ppw(G). A proper-path-decomposition of width k is called a k-proper-path-decomposition.

A graph H is a minor of a graph G if H is isomorphic to a graph obtained from a subgraph of G by contracting edges. A family \mathcal{F} of graphs is said to be minor-closed if the following condition holds: If $G \in \mathcal{F}$ and H is a minor of G then $H \in \mathcal{F}$. A graph G is a minimal forbidden minor for a minor-closed family \mathcal{F} of graphs if $G \notin \mathcal{F}$ and any proper minor of G is in \mathcal{F} . \mathcal{F} is characterized by the minimal forbidden minors for \mathcal{F} . That is, a graph G is in \mathcal{F} if and only if no minimal forbidden minor for \mathcal{F} is a minor of G. For a positive integer k, the family \mathcal{P}_k of graphs with proper-pathwidth at most k is minor-closed. K_3 and $K_{1,3}$ are the minimal forbidden minors for \mathcal{P}_1 [6], and 36 graphs are known as the minimal forbidden minors for \mathcal{P}_2 [7]. The five minimal forbidden minors for \mathcal{P}_2 shown in Fig. 1 will be used in Sect. 4.

3. Characterization

In this section, we characterize graphs with maximum vertex degree 3 and proper-pathwidth 2.

Suppose that G' is a graph obtained from a graph G by deleting self-loops and replacing multiple edges with a single edge. A proper-path-decomposition of G' is also that of G, and vice versa, by definition. Therefore, an optimal proper-path-decomposition of G' is also that of G. An optimal proper-path-decomposition of a graph can be obtained by concatenating optimal proper-path-decompositions of connected components. From these facts, we assume that the graphs considered in the rest of the paper are simple and connected.

A cut vertex of a graph G is called a connection point of G if the vertex is contained in a 2-connected block of G. Since a connection point of G is a cut vertex of G, E(G) can be partitioned into disjoint sets E_1, \ldots, E_l such that $G[E_i]$ and $G[E_j]$ share at most one connection point of G for any i and j with $1 \le i < j \le l$. Let $\mathcal{D} = \{G[E_i] \mid 1 \le i \le l\}$. We define that \mathcal{H} is the set of 2-connected components in \mathcal{D} . A component of $\mathcal{D} - \mathcal{H}$ is called a path component of G if the component is a path. \mathcal{P} denotes the set of path components of G. A component of $\mathcal{D} - (\mathcal{H} \cup \mathcal{P})$ is called a tree component of G. \mathcal{T} denotes the set of tree components of G.

The following characterization for trees with proper-pathwidth at most k is given in [9].

Lemma A: For a tree T and an integer $k \geq 2$, $ppw(T) \leq k$ if and only if there exists a path P in T such that $ppw(T - V(P)) \leq k - 1$. \Box k-spine of T is a path satisfying the condition of Lemma A.

The following is the main theorem of the paper.

Theorem 1: For a graph G with $\Delta(G) \leq 3$, $ppw(G) \leq 2$ if and only if G has a sequence $C = (C_1, C_2, \ldots, C_m)$ of distinct components in \mathcal{D} and a sequence $\mathcal{A} = (a_0, a_1, \ldots, a_m)$ of distinct vertices of G such that the following condition is satisfied. Let $\mathcal{D}' = \mathcal{D} - \{C_i \mid 1 \leq i \leq m\}$.

Condition 2:

- (a) $V(C_i) \cap V(C_{i+1}) = \{a_i\}$ for $1 \le i < m$, $a_0 \in V(C_1)$, and $a_m \in V(C_m)$.
- (b) $\deg_G(a_0) \leq 2$ and $\deg_G(a_m) \leq 2$.
- (c) For $1 \leq i \leq m$, if $C_i \in \mathcal{T}$ then the path in C_i connecting a_{i-1} and a_i is a 2-spine of C_i .
- (d) For $1 \leq i \leq m$, if $C_i \in \mathcal{H}$ then C_i is an outer planar graph with at most two end-regions. Moreover, each end-region contains a_{i-1} or a_i .
- (e) $\mathcal{D}' \subseteq \mathcal{P}$.
- (f) There exists a one-to-one mapping $f: \mathcal{D}' \to \{i \mid 1 \leq i \leq m\} \times \{0,1\}$ satisfying the following statement.

For $P \in \mathcal{D}'$, f(P) = (i, j) if and only if $C_i \in \mathcal{H}$ and there exists an end-vertex x of P such that $(x, a_{i-j}) \in E(C_i)$. (*)

In the following section, we give a constructive proof for Theorem 1, and based on the proof, we describe a linear time algorithm which, given a graph G with $\Delta(G) \leq 3$, determines whether $ppw(G) \leq 2$, and if so, constructs a proper-path-decomposition of width at most 2 of G.

4. Proof and Algorithm

We first prove the theorem for a special case of $|\mathcal{D}| = 1$. We prove the theorem for trees and 2-connected graphs in Sect. 4.1 and 4.2, respectively. The proof for general case is given in Sect. 4.3. We also give in Sect. 4.3 an algorithm for general graphs.

For a sequence $\mathcal{X} = (X_1, X_2, \dots, X_r)$ of elements, X_1 and X_r are called the *head* of \mathcal{X} and its *tail*, respectively. We denote the sequence without elements by *nul*. For sequences $\mathcal{X} = (X_1, X_2, \dots, X_r)$ and $\mathcal{Y} = (Y_1, Y_2, \dots, Y_q)$, we define that $\mathcal{X} + \mathcal{Y} = (X_1, X_2, \dots, X_r, Y_1, Y_2, \dots, Y_q)$. For a sequence $\mathcal{X} = (X_1, X_2, \dots, X_r)$ of subsets of a set Ω and $W \subseteq \Omega$, we define that $\mathcal{X} \cup W = (X_1 \cup W, X_2 \cup W, \dots, X_r \cup W)$ and $\mathcal{X} \cap W = (X_1 \cap W, X_2 \cap W, \dots, X_r \cap W)$.

4.1 Binary Trees

Theorem 1 is immediate for binary trees by Lemma A. An algorithm for constructing optimal proper-path-decompositions of trees is shown in [8]. Since this algorithm computes ppw(T) in O(N) time for an N-vertex tree T and provides an optimal proper-path-decomposition of T in O(Nppw(T)) time, we can construct a 2-proper-path-decomposition of T with ppw(T) = 2 in linear time.

In this subsection, we show algorithms for constructing a proper-path-decomposition of a binary tree with width at most 2 satisfying some conditions. These algorithms will be used to construct an algorithm for general graphs.

Lemma 2: For a path $P = (p_0, \ldots, p_l)$, there exists a 1-proper-path-decomposition $\mathcal{X} = (X_1, \ldots, X_r)$ of P such that $p_0 \in X_1$ and $p_l \in X_r$.

Proof: Let $\mathcal{X} = (X_1, \dots, X_l)$ with $X_i = \{p_{i-1}, p_i\}$ $(1 \leq i \leq l)$ if $l \geq 1$, $\mathcal{X} = (\{p_0\})$ otherwise. \mathcal{X} is clearly a desired proper-path-decomposition.

Algorithm PPD_PATH shown in Fig. 2 is the formal description of the procedure written in the proof of Lemma 2. Trivially, PPD_PATH can be executed in linear time.

Lemma 3: For a binary tree T with ppw(T) = 2 and its 2-spine $P = (p_0, \ldots, p_l)$ such that

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Procedure PPD_PATH ( P ) \begin{bmatrix} \text{Input: a path } P = (p_0, p_1, \dots, p_l); \\ \text{Output: a 1-proper-path-decomposition } (X_1, X_2, \dots, X_r) \\ \text{of } P \text{ such that } p_0 \in X_1 \text{ and } p_l \in X_r; \\ \end{bmatrix}
1. \text{ if } l = 0 \text{ then return } (\{p_0\});
2. \text{ for each } 1 \leq i \leq l \text{ do}
X_i := \{p_{i-1}, p_i\};
\text{endfor } ;
3. \text{ return } (X_1, X_2, \dots, X_l);
End
```

Fig. 2 Algorithm for constructing a 1-proper-path-decomposition of a path.

 $\deg_T(p_0) = \deg_T(p_l) = 1$, there exists a 2-properpath-decomposition $\mathcal{X} = (X_1, \dots, X_r)$ of T such that $p_0 \in X_1 - \bigcup_{1 \le i \le r} X_i$ and $p_l \in X_r - \bigcup_{1 \le i < r} X_i$.

Proof: Since P is a 2-spine of T, it follows from Lemma A that $ppw(T-V(P)) \leq 1$. Thus, each connected component of T-V(P) is a path. For 0 < i < l, at most one connected component P_i of T-V(P) has a vertex adjacent to p_i since $\Delta(T) \leq 3$. Let $I = \{i \mid 0 < i < l, \deg_T(p_i) = 3\}$. We define the sequence \mathcal{X} of subsets of V(T) as follows:

$$\begin{split} \mathcal{X} &= (S_1) + \mathcal{Y}_1 + (S_2) + \dots + (S_{l-1}) + \mathcal{Y}_{l-1} + (S_l), \\ \text{where for } 1 \leq i \leq l, \\ S_i &= \left\{ \begin{array}{l} \{p_{i-1}, p_i\} \cup V(P_i) \\ & \text{if } i \in I \text{ and } |V(P_i)| = 1 \\ \{p_{i-1}, p_i\} & \text{otherwise} \end{array} \right. \\ \text{for } 1 \leq i < l, \\ \mathcal{Y}_i &= \left\{ \begin{array}{l} \text{PPD_PATH}(P_i) \cup \{p_i\} \\ & \text{if } i \in I \text{ and } |V(P_i)| \geq 2 \\ nul & \text{otherwise} \end{array} \right. \end{split}$$

We show that \mathcal{X} is a desired 2-proper-path-decomposition. The following claim can be easily observed from the definition of \mathcal{X} .

Claim 4:

- 1. p_0 and p_l appear in S_1 and S_l , respectively.
- 2. For 0 < i < l, p_i appears in $S_i \cap S_{i+1}$. Moreover, p_i appears in every element of \mathcal{Y}_i if $\mathcal{Y}_i \neq nul$.
- 3. For $i \in I$ with $|V(P_i)| \ge 2$, $v \in V(P_i)$ appears in at most two consecutive elements of \mathcal{Y}_i .
- 4. For $i \in I$ with $|V(P_i)| = 1$, $v \in V(P_i)$ appears in S_i .

It is clear by Claim 4 that \mathcal{X} satisfies (a), (b), and (c) in Condition 1. Moreover, \mathcal{X} satisfies (d) in Condition 1 since we can observe that any vertex of T appears in consecutive elements of \mathcal{X} . In what follows, we show that \mathcal{X} satisfies (e) in Condition 1. If $X_a \cap X_c = \emptyset$ for all a and c with $1 < a+1 \le c-1 < r$ then the condition is clearly satisfied. Thus, we assume that there exist a

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Input: a binary tree T;
           a 2-spine P = (p_0, \ldots, p_l) of T such that
           \deg_T(p_0) = \deg_T(p_l) = 1;
 Output: a proper-path-decomposition (X_1, \ldots, X_r) of T
           with width at most 2 such that p_0 \in X_1 - \bigcup_{1 < i \le r} X_i and p_l \in X_r - \bigcup_{1 \le i < r} X_i;
1. for i := 1 to l-1 do
      a. S_i := \{p_{i-1}, p_i\};
      b. \mathcal{Y}_i := nul;
      c. if \deg_T(p_i) = 3 then
             i. let P_i be the connected component in T-V(P)
                which has a vertex adjacent to p_i in T;
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endfor;

Procedure PPD_TREE (T, P)

2. $S_l := \{p_{l-1}, p_l\};$ 3. return $(S_1) + \mathcal{Y}_1 + (S_2) + \cdots + (S_{l-1}) + \mathcal{Y}_{l-1} + (S_l)$;

else $\mathcal{Y}_i := PPD_PATH(P_i) \cup \{p_i\};$

ii. if $|V(P_i)|=1$ then $S_i:=\{p_{i-1},p_i\}\cup V(P_i);$

Fig. 3 Algorithm for constructing a 2-proper-pathdecomposition of a binary tree with its 2-spine.

and c with $1 < a+1 \le c-1 < r$ such that $X_a \cap X_c \neq \emptyset$. Since any vertex in $V(T) - \{p_i \mid i \in I, |V(P_i)| \ge 2\}$ appears in at most two consecutive elements of \mathcal{X} , there exists p_i such that $i \in I$, $|V(P_i)| \ge 2$, and $p_i \in X_a \cap X_c$. Since (X_a, \ldots, X_c) is a subsequence of $(S_i) + \mathcal{Y}_i + (S_{i+1})$, no vertices in $V(P) - \{p_i\}$ are contained in $X_a \cap X_c$. Moreover, since X_b is an element of \mathcal{Y}_i for any b with a < b < c, it follows from $|V(P_i)| \ge 2$ that $|X_b| = 3$. Thus, we have that $|X_a \cap X_c| = |\{p_i\}| = 1 \le |X_b| - 2$ for any b with a < b < c. Therefore, \mathcal{X} satisfies (e) in Condition 1. It is clear that the width of \mathcal{X} is at most 2 and that $p_0 \in X_1 - \bigcup_{1 \le i \le r} X_i$ and $p_l \in X_r - \bigcup_{1 \le i \le r} X_i$. Therefore, \mathcal{X} is a desired proper-path-decomposition.

We describe Algorithm PPD_TREE based on Lemma 3 in Fig. 3. The following corollary is immedi-

Corollary 5: Given a binary tree T and a 2-spine $P = (p_0, \dots, p_l)$ of T such that $\deg_T(p_0) = \deg_T(p_l) =$ 1, PPD_TREE outputs in linear time a proper-pathdecomposition (X_1, \ldots, X_r) of T with width at most 2 such that $p_0 \in X_1 - \bigcup_{1 < i \le r} X_i$ and $p_l \in X_r$ $\bigcup_{1 \leq i \leq r} X_i$.

4.2 2-Connected Graphs

In this subsection, we show a necessary and sufficient condition for a 2-connected graph G to have ppw(G) =2, and based on this condition, we give an algorithm for constructing a 2-proper-path-decomposition of G. This algorithm is used in the next subsection to construct an algorithm for general graphs.

Theorem 1 is immediate for 2-connected graphs by

the following lemma.

Lemma 6: For a 2-connected graph G, ppw(G) = 2if and only if G is outer planar and has at most two end-regions.

Proof: First, we assume that ppw(G) = 2. Then none of M_1 , K_4 , and $K_{2,3}$ which are shown in Fig. 1 is a minor of G. It is well-known that the family of outer planar graphs is minor-closed and that K_4 and $K_{2,3}$ are the minimal forbidden minors for the family of outer planar graphs. Thus G is outer planar. Moreover, Ghas at most two end-regions since M_1 is not a minor of G.

Next, we assume that G is outer planar and has at most two end-regions. Let e_s and e_t be any edges in Gsatisfying the following condition:

Condition 3: e_s and e_t are outer edges contained in distinct end-regions if G has two end-regions.

It suffices to show the following claim.

Claim 7: There exists a 2-proper-path-decomposition $\mathcal{X} = (X_1, \dots, X_r)$ of G such that

$$|X_i| = 3 \ (1 \le i \le r),$$
 (1)

$$e_s \in E(G[X_1]) - E(G[\bigcup_{1 \le i \le r} X_i]), \text{ and}$$
 (2)

$$e_s \in E(G[X_1]) - E(G[\bigcup_{1 < i \le r} X_i]), \text{ and}$$
 (2)
 $e_t \in E(G[X_r]) - E(G[\bigcup_{1 \le i < r} X_i]).$ (3)

We prove this claim by induction on |V(G)|.

If |V(G)| = 3 then $\mathcal{X} = (V(G))$ is clearly a desired proper-path-decomposition.

We assume that the claim holds for any G' with $|V(G)|-1 \ge 3$ vertices and for any pair of edges in G'satisfying Condition 3. Since $|V(G)| \ge 4$, there exists a degree 2 vertex s incident to e_s but not to e_t . Suppose that $e_s = (s, y)$ and $N_G(s) - \{y\} = \{x\}$. Let G' be the graph obtained by contracting the edge (s, x). Since s is identified with x, we denote the resulting vertex of G' by x. G' is clearly an outer planar graph with at most two end-regions. By the definitions of s, x, and y, (x,y) and e_t are distinct edges in G' satisfying Condition 3. Therefore, by induction hypothesis, there exists a 2-proper-path-decomposition $\mathcal{Y} = (Y_1, \dots, Y_l)$ of G'such that

$$|Y_i| = 3 \ (1 \le i \le l), \tag{4}$$

$$(x,y) \in E(G'[Y_1]) - E(G'[\bigcup_{1 < i \le l} Y_i]), \text{ and}$$

$$e_t \in E(G'[Y_l]) - E(G'[\bigcup_{1 \le i < l} Y_i]).$$

$$(5)$$

$$e_t \in E(G'[Y_l]) - E(G'[\bigcup_{1 \le i < l} Y_i]). \tag{6}$$

We show that $\mathcal{X} = (\{s, x, y\}) + \mathcal{Y}$ is a desired 2-properpath-decomposition of G.

We first show that \mathcal{X} satisfies (1), (2), and (3). It follows from (4) and the definition of \mathcal{X} that \mathcal{X} satisfies (1). Since

$$s \notin Y_i \ (1 \le i \le l), \tag{7}$$

we have that

$$e_s \in E(G[\{s, x, y\}]) - E(G[\bigcup_{1 \le i \le l} Y_i]). \tag{8}$$

It follows from (6) and (8) that \mathcal{X} satisfies (2) and (3).

We next show that \mathcal{X} is a 2-proper-path-decomposition of G. \mathcal{X} clearly satisfies (a), (b), and (c) in Condition 1. Since \mathcal{Y} is a proper-path-decomposition of G' and $|Y_i| = 3$ for all i with $1 \leq i \leq l$, it follows that

$$Y_a \cap Y_c \subseteq Y_b \ (1 \le a \le b \le c \le l),$$

$$|Y_a \cap Y_c| \le |Y_b| - 2 \ (1 \le a < b < c \le l).$$

$$(9)$$

Thus, to show that \mathcal{X} satisfies (d) and (e) in Condition 1, it suffices to prove that $\{s, x, y\} \cap Y_c \subseteq Y_b$ and $|\{s, x, y\} \cap Y_c| \leq |Y_b| - 2$ for $1 \leq b < c \leq l$. It follows from (5) that

$$\{x,y\} \subseteq Y_1, \tag{10}$$

$$\{x,y\} \subseteq \bigcup_{1 < i \le l} Y_i. \tag{11}$$

It follows from (7), (9), and (10) that $\{s, x, y\} \cap Y_c = \{x, y\} \cap Y_c \subseteq Y_1 \cap Y_c \subseteq Y_b \text{ for } 1 \leq b < c \leq l.$ It follows from (7) and (11) that $|\{s, x, y\} \cap Y_c| \leq 1$ for $1 < c \leq l$. Thus we have that $|\{s, x, y\} \cap Y_c| \leq |Y_b| - 2$ for $1 \leq b < c \leq l$ by (4).

Therefore,
$$\mathcal X$$
 is a desired 2-proper-path-decomposition of G , and we conclude that the lemma holds. \Box

We describe in Fig. 4 Algorithm PPD_2CG based on Lemma 6.

Corollary 8: Given a 2-connected outer planar graph G with at most two end-regions and any edges e_s and e_t in G satisfying Condition 3, PPD_2CG outputs in linear time a 2-proper-path-decomposition (X_1, \ldots, X_r) of G satisfying (1), (2), and (3).

Proof: The correctness of PPD_2CG is immediate from the proof of Lemma 6. PPD_2CG involves |V(G)| recursive calls each of which consists of constant time operations. Therefore, PPD_2CG can be executed in linear time.

4.3 General Graphs

In this subsection, we prove Theorem 1 and describe our algorithm for general graphs. The following lemma will be used extensively throughout this subsection. Procedure PPD_2CG (G, e_s , e_t)

Input: a 2-connected outer planar graph G with at most two end-regions; edges e_s and e_t satisfying Condition 3; Output: a 2-proper-path-decomposition (X_1, \ldots, X_r) of G satisfying (1), (2), and (3);

- 1. if |V(G)| = 3 then return (V(G));
- 2. Let s be a vertex such that $\deg_G(s)=2, e_s\in \Gamma(s)$, and $e_t\notin \Gamma(s)$;
- 3. let $\{x,y\} := N_G(s)$ such that $(s,y) = e_s$;
- 4. let G' be the graph obtained from G by contracting (s, x);
- 5. return $(\{s, x, y\}) + PPD_2CG(G', (x, y), e_t);$

End

Fig. 4 Algorithm for constructing a 2-proper-path-decomposition of a 2-connected graph.

Lemma 9: Let $\mathcal{X} = (X_1, \dots, X_r)$ be a 2-proper-path-decomposition of a graph G with ppw(G) = 2. For a path P connecting a vertex $s \in X_1$ and a vertex $t \in X_r$, every connected component of G - V(P) is a path.

Proof: Suppose that $\mathcal{Y}=(Y_1,\ldots,Y_r)$ is $\mathcal{X}\cap(V(G)-V(P))$. It suffices to show that the sequence \mathcal{Y}' obtained from \mathcal{Y} by deleting redundant elements is a 1-proper-path-decomposition of G-V(P). \mathcal{Y} clearly satisfies (b), (c), and (d) in Condition 1 for G-V(P). Thus, \mathcal{Y}' satisfies (a), (b), (c), and (d) in Condition 1 for G-V(P). To show that \mathcal{Y}' satisfies (e) in Condition 1, it suffices to prove that both of the following statements holds: (i) $|Y_i| \leq 2$ for any $1 \leq i \leq r$; (ii) $Y_a = Y_c$ or $|Y_a \cap Y_c| = 0$ for all a and c with $1 < a + 1 \leq c - 1 < r$. Every X_i ($1 \leq i \leq r$) contains a vertex of P since end-vertices s and t of P are contained in X_1 and X_t , respectively, and \mathcal{X} satisfies (c) and (d) in Condition 1. Since the width of \mathcal{X} is 2, we have that $|Y_i| \leq 2$, i.e. (i) holds.

Since \mathcal{X} satisfies (e) in Condition 1, we have that

$$|X_a \cap X_c| \le |X_b| - 2 \le 3 - 2 = 1 \tag{12}$$

for any a, b, and c with $1 \le a < b < c \le r$. For a, b, and c with $1 \le a < b < c \le r$, let $p_a \in X_a \cap V(P)$, $p_b \in X_b \cap V(P)$, and $p_c \in X_c \cap V(P)$.

Case 1 $p_a = p_c$. It follows from (12) that $|X_a \cap X_c| = 1$. Thus, we have $|Y_a \cap Y_c| = 0$.

Case 2 $p_a \neq p_c$. It suffices to show that, if $|Y_a \cap Y_c| = 1$ then $Y_a = Y_c$. We assume that $|Y_a \cap Y_c| = 1$, and show that $Y_a = Y_c$. Let $v \in Y_a \cap Y_c$. It follows from (d) in Condition 1 that $v \in Y_b \subset X_b$. Now we show that $X_b - (V(P) \cup \{v\}) = \emptyset$. We prove this by contradiction. Assume that $X_b - (V(P) \cup \{v\}) \neq \emptyset$. Since $|X_b| \leq 3$, it follows from assumption that $X_b \cap V(P) = \{p_b\}$. Since P connects $s \in X_1$ and $t \in X_r$, it follows from 1 < b < r that $p_b \in X_{b-1} \cap X_{b+1}$. Moreover, since $v \in Y_a \cap Y_c$ and \mathcal{X} satisfies (d) in Condition 1, we have that $v \in X_{b-1} \cap X_{b+1}$. Thus, we

have that $|X_{b-1} \cap X_{b+1}| \ge |\{p_b, v\}| = 2$, contradicting (12). Therefore, it follows that $X_b - (V(P) \cup \{v\}) = \emptyset$. Since this holds for any b with a < b < c, we have $Y_a = Y_{a+1} = \cdots = Y_c = \{v\}$.

Therefore, (ii) holds.

In what follows, G is a graph with $\Delta(G) = 3$. Let \mathcal{H} , \mathcal{T} , and \mathcal{P} be the sets of 2-connected components, tree components, and path components of G, respectively, and $\mathcal{D} = \mathcal{H} \cup \mathcal{T} \cup \mathcal{P}$.

Proof of Necessity for Theorem 1

We first show the necessity. Assume that ppw(G) = 2. Since the theorem is proved for the case of $|\mathcal{D}| = 1$ in Sect. 4.1 and 4.2, we assume that $|\mathcal{D}| \geq 2$. It follows from assumption that $|V(G)| \geq 4$. There exists a 2-proper-path-decomposition $\mathcal{X} = (X_1, \dots, X_r)$ of G. Since \mathcal{X} satisfies (a) in Condition 1 and $|V(G)| \geq 4$, there exist $s \in X_1 - X_2$ and $t \in X_r - X_{r-1}$. We define that S is a path connecting s and t.

Claim 10: For $D \in \mathcal{D}$, $D \cap S$ is connected if $D \cap S$ has a vertex.

Proof: By the definitions of 2-connected components, tree components, and path components, every path in G connecting vertices of D is a subgraph of D. Thus, the claim holds.

Let C_1, C_2, \ldots, C_m be components in $\mathcal D$ containing an edge of S. By Claim $10, C_i \cap S$ is a subpath of S ($1 \leq i \leq m$). Moreover, $C_i \cap S$ and $C_j \cap S$ are internally vertex-disjoint since C_i and C_j share at most one connection point for $1 \leq i < j \leq m$. Thus we may assume without loss of generality that $C_i \cap S$ and $C_{i+1} \cap S$ share a connection point a_i for $1 \leq i < m$. Let $a_0 = s$ and $a_m = t$. Notice that a_{i-1} and a_i are end-vertices of $C_i \cap S$ for $1 \leq i \leq m$. Moreover, a_{i-1} and a_i are distinct vertices since $C_i \cap S$ has at least two vertices for $1 \leq i \leq m$. This means that a_0, a_1, \ldots, a_m are distinct vertices of G. We define that $C = (C_1, C_2, \ldots, C_m)$ and $C = (a_0, a_1, \ldots, a_m)$. We show that $C = (a_0, a_1, \ldots, a_m)$.

 \mathcal{C} and \mathcal{A} clearly satisfies (a) in Condition 2 by definition. The following claim shows that \mathcal{C} and \mathcal{A} satisfies (b) in Condition 2.

Claim 11: $\deg_G(s) \leq 2$ and $\deg_G(t) \leq 2$.

Proof: $|X_1| \leq 3$ and $|X_r| \leq 3$ since the width of \mathcal{X} is 2. Thus, we have $\deg_G(s) \leq 2$ and $\deg_G(t) \leq 2$ since s is only in X_1 and t is only in X_r .

The following claim shows that $\mathcal C$ and $\mathcal A$ satisfy (c) in Condition 2.

Claim 12: If $C_i \in \mathcal{T}$ $(1 \leq i \leq m)$, then the path in C_i connecting a_{i-1} and a_i is a 2-spine of C_i .

Proof: Let S' be the path in C_i connecting a_{i-1} and a_i . By Lemma 9, every connected component of G - V(S) is a path. Since S' is a subpath of S, every connected component of $C_i - V(S')$ is a path. This means that S' is a 2-spine of C_i .

The following claim shows that C and A satisfy (d) in Condition 2. Let $P_i^s = (s, \ldots, a_i)$ and $P_i^t = (a_i, \ldots, t)$ be the subpaths of S for $0 \le i \le m$.

Claim 13: If $C_i \in \mathcal{H}$ $(1 \leq i \leq m)$, then C_i is an outer planar graph with at most two end-regions. Moreover, each end-region contains a_{i-1} or a_i .

Proof: Suppose that $C_i \in \mathcal{H}$ $(1 \leq i \leq m)$. Since ppw(G) = 2, we have that $ppw(C_i) = 2$. Thus, C_i is an outer planar graph with at most two end-regions from Lemma 6. It remains to show that each end-region of C_i contains a_{i-1} or a_i . If C_i has an end-region Z which contains neither a_{i-1} nor a_i , then there exists a path \overline{P} in C_i which connects a_{i-1} and a_i and contains no vertices in Z. $S' = P_{i-1}^s \cup \overline{P} \cup P_i^t$ is clearly a path connecting S and S are vertex-disjoint, S on S contains a cycle as a subgraph. However, this contradicts Lemma 9. Thus, each end-region of S contains S or S or S or S.

The following claim shows that C and A satisfy (e) in Condition 2. Let $D' = D - \{C_i \mid 1 \le i \le m\}$.

Claim 14: $\mathcal{D}' \subseteq \mathcal{P}$.

Proof: We show that any $D \in \mathcal{H} \cup \mathcal{T}$ is an element of \mathcal{C} . By Claim 10 and the definition of \mathcal{C} , it suffices to show that $|V(D \cap S)| \geq 2$. By Lemma 9, $D \cap S$ has at least one vertex. Thus it remains to show that $|V(D \cap S)| \neq 1$. We prove this by contradiction. Assume that $V(D \cap S) = \{x\}$.

Case 1 $D \in \mathcal{H}$. If $x \in V(S) - \{s,t\}$ then we have $\deg_G(x) = \deg_D(x) + \deg_S(x) \ge 2 + 2 = 4$, which is a contradiction since $\Delta(G) = 3$. If $x \in \{s,t\}$ then we have $\deg_G(x) = \deg_D(x) + \deg_S(x) \ge 2 + 1 = 3$, which also contradicts Claim 11.

Case 2 $D \in \mathcal{T}$. Since there exists an edge in $\Gamma_S(x)$ which is not contained in D, x is a connection point of G. Thus, there exists $H \in \mathcal{H}$ containing x. Since H is 2-connected and $\Delta(G) = 3$, x is incident to just two edges of H and to exactly one edge of D. Thus, it follows from Claim 11 that $x \notin \{s, t\}$ and S has two edges in $\Gamma_H(x)$. This means that H is an element of C and $x \notin \{a_i \mid 0 \le i \le m\}$. Suppose that $H = C_i$ $(1 \le i \le m)$. Since C_i is 2-connected, there exists a path \overline{P} in C_i which connects a_{i-1} and a_i and does not contain x. $S' = P^s_{i-1} \cup \overline{P} \cup P^t_i$ is a path connecting s and s and

Thus, we conclude that $|V(D \cap S)| \neq 1$ and the claim holds.

We prove by a sequence of claims that \mathcal{C} and \mathcal{A} satisfy (f) in Condition 2. It is clear that $P \in \mathcal{D}'$ has exactly one connection point. We denote the connection point by c(P).

Claim 15: For $P \in \mathcal{D}'$, there exists a unique $C_i \in \mathcal{H}$ $(1 \leq i \leq m)$ such that $c(P) \in V(C_i)$. Moreover, $(c(P), a_{i-1}) \in E(C_i)$ or $(c(P), a_i) \in E(C_i)$.

Proof: Since $\Delta(G) = 3$, it is clear that for $P \in \mathcal{D}'$, there exists a unique $C_i \in \mathcal{H}$ $(1 \leq i \leq m)$ such that $c(P) \in V(C_i)$. We show that $(c(P), a_{i-1}) \in E(C_i)$ or $(c(P), a_i) \in E(C_i)$. We prove this by contradiction. Assume that $(c(P), a_{i-1}) \notin E(C_i)$ and $(c(P), a_i) \notin E(C_i)$. c(P) is neither a_{i-1} nor a_i from Claim 11 and the assumption that $\Delta(G) = 3$. Thus, neither a_{i-1} nor a_i is contained in $N_G(c(P)) \cup \{c(P)\}$. Since C_i is 2-connected outer planar graph with $\Delta(G) = 3$, c(P) is incident to just two outer edges of C_i and to exactly one edge of P. Thus, there exists a path P in C_i which connects a_{i-1} and a_i and does not contain a vertex incident to the two outer edges. $S' = P_{i-1}^s \cup \overline{P} \cup P_i^t$ is a path connecting s and t. Since S' has no vertex adjacent to c(P), G - V(S') has c(P) with degree 3, contradicting Lemma 9.

Claim 16: For distinct $P_1, P_2 \in \mathcal{D}'$, $c(P_1) \neq c(P_2)$.

Proof: Each $c(P_i)$ (i=1,2) is contained in a 2-connected component of G by Claim 15. If $c(P_1)=c(P_2)$ then $\deg_G(c(P_i))\geq 4$ (i=1,2), contradicting the assumption that $\Delta(G)=3$.

Claim 17: Suppose that $C_i \in \mathcal{H}$ $(1 \leq i \leq m)$. If there exist distinct $P_1, P_2 \in \mathcal{D}'$ such that both $c(P_1)$ and $c(P_2)$ are adjacent to $a \in \{a_{i-1}, a_i\}$, then $c(P_1)$ or $c(P_2)$ is adjacent to $a' \in \{a_{i-1}, a_i\} - \{a\}$.

Proof: We show the claim by contradiction. Assume that there exist distinct $P_1, P_2 \in \mathcal{D}'$ such that both $c(P_1)$ and $c(P_2)$ are adjacent to $a \in \{a_{i-1}, a_i\}$ and that neither $c(P_1)$ nor $c(P_2)$ is adjacent to $a' \in \{a_{i-1}, a_i\} - \{a\}$. Let L be the subgraph of G induced by all the outer edges of C_i . Suppose that $N_L(a') = \{u, v\}$. It follows from the assumption and Claims 15 and 16 that $a, a', u, v, c(P_1)$, and $c(P_2)$ are distinct vertices.

If there exists an edge $e \in E(G) - E(C_i)$ incident to a', then M_3 shown in Fig. 1 is a minor of the subgraph $L \cup P_1 \cup P_2 \cup G[\{e\}]$ of G, i.e. ppw(G) > 2. This means that $\Gamma_G(a') - E(C_i) = \emptyset$ and that the properpathwidth of the graph G' obtained from G by adding an additional vertex x and by joining a' and x by an additional edge is more than 2. If $a' = a_j$ $(1 \le j < m)$ then $\Gamma_G(a') - E(C_i) \neq \emptyset$ clearly. Thus we have that $a' = a_0(=s)$ or $a' = a_m(=t)$. Let $\mathcal{X}' = (\{x,s\}) + \mathcal{X}$ if a' = s, $\mathcal{X}' = \mathcal{X} + (\{t,x\})$ otherwise. It is not difficult to see that \mathcal{X}' is a proper-path-decomposition of G' and that the width of \mathcal{X}' is 2. This means that ppw(G') = 2, a contradiction.

Claim 18: For $C_i \in \mathcal{H} \ (1 \le i \le m), \ |\{P \in \mathcal{D}' \mid c(P) \in V(C_i)\}| \le 2.$

Proof: We show the claim by contradiction. Assume that there exist distinct $P_1, P_2, P_3 \in \mathcal{D}'$ such that $\{c(P_1), c(P_2), c(P_3)\} \subseteq V(C_i)$. Let L be the subgraph of G induced by all the outer edges of C_i . Moreover, let G' be the graph obtained from G by adding additional vertices x and y and edges (x, s) and (y, t). Notice that there exist distinct edges $e \in \Gamma_{G'}(a_{i-1}) - E(C_i)$ and $e' \in \Gamma_{G'}(a_i) - E(C_i)$. As shown in the proof of Claim 15,

 $\{c(P_1), c(P_2), c(P_3)\} \cap \{a_{i-1}, a_i\} = \emptyset$. Thus it follows from Claim 16 that $c(P_1), c(P_2), c(P_3), a_{i-1}$, and a_i are distinct vertices. Therefore, M_2 shown in Fig. 1 is a minor of the subgraph $L \cup P_1 \cup P_2 \cup P_3 \cup G'[\{e, e'\}]$ of G', i.e. ppw(G') > 2. However, it is not difficult to see that $\mathcal{X}' = (\{x, s\}) + \mathcal{X} + (\{t, y\})$ is a proper-path-decomposition of G' and that the width of \mathcal{X}' is 2. Thus we have ppw(G') = 2, a contradiction.

Claim 19: C and A satisfy (f) in Condition 2.

Proof: It follows from Claim 15 that there exists a mapping f satisfying the statement (*) in Condition 2. By Claims 17 and 18, f can easily be reconstructed so that it is a one-to-one mapping satisfying (*).

Thus, C and A satisfy Condition 2. Therefore, the proof of necessity for Theorem 1 is completed.

Proof of Sufficiency for Theorem 1

We next show the sufficiency. Assume that G has a sequence $\mathcal{C} = (C_1, C_2, \ldots, C_m)$ of components in \mathcal{D} and a sequence $\mathcal{A} = (a_0, a_1, \ldots, a_m)$ of vertices of G such that Condition 2 is satisfied. If $C_1 \in \mathcal{T}$ and $\deg_G(a_0) = 2$ then we can easily find a vertex $a'_0 \in V(C_1)$ such that $\deg_G(a'_0) = 1$ and that the path connecting a'_0 and a_1 is a 2-spine of C_1 . Moreover, \mathcal{C} and the sequence (a'_0, a_1, \ldots, a_m) satisfy Condition 2. Thus, we assume without loss of generality that, if $C_1 \in \mathcal{T}$ then $\deg_G(a_0) = 1$. Similarly, we assume without loss of generality that, if $C_m \in \mathcal{T}$ then $\deg_G(a_m) = 1$.

For $C_i \in \mathcal{H}$ $(1 \leq i \leq m)$, we define that e_i^0 and e_i^1 are distinct edges of C_i incident to a_i and a_{i-1} , respectively, such that if there exists $P \in \mathcal{D}'$ with f(P) = (i, j) then $e_i^j = (a_{i-j}, c(P))$ (j = 0, 1). The following claim shows that e_i^0 and e_i^1 satisfy Condition 3 for $C_i \in \mathcal{H}$.

Claim 20: For $C_i \in \mathcal{H}$, e_i^0 and e_i^1 are outer edges of C_i . Moreover, they are contained in distinct endregions if C_i has two end-regions.

Proof: The claim is immediate if C_i has a single endregion. Thus, we assume C_i has two end-regions. Since (b) in Condition 2 is satisfied and $\Delta(G)=3$, we have that $\deg_{C_i}(a_{i-1})=\deg_{C_i}(a_i)=2$. Thus, two edges incident to $a\in\{a_{i-1},a_i\}$ are outer edges contained in a same region. Moreover, since (d) in Condition 2 is satisfied, a_{i-1} and a_i are contained in distinct end-regions. Therefore, $\Gamma_{C_i}(a_{i-1})$ and $\Gamma_{C_i}(a_i)$ are subsets of edges of distinct end-regions. Since $e_i^j\in\Gamma_{C_i}(a_{i-j})$ (j=0,1), the claim holds.

We show that the sequence $\mathcal{X} = (X_1, \dots, X_r)$ of subsets of V(G) defined as follows is a 2-proper-path-decomposition of G.

$$\mathcal{X} = \sum_{1 \le i \le m} \mathcal{L}^i + \mathcal{Y}^i + \mathcal{R}^i$$
, where for $1 \le i \le m$,

$$\mathcal{Y}^i = \begin{cases} \text{PPD_TREE}(C_i, \text{path } (a_{i-1}, \dots, a_i)) \\ & \text{if } C_i \in \mathcal{T} \cup \mathcal{P} \\ \text{PPD_2CG}(C_i, e_i^1, e_i^0) & \text{if } C_i \in \mathcal{H} \end{cases}$$

$$\mathcal{L}^i = \begin{cases} \text{PPD_PATH}(P = (p_0, \dots, c(P))) \cup \{a_{i-1}\} \\ & \text{if } \exists P \in \mathcal{D}' \text{ with } f(P) = (i, 1) \\ & nul & \text{otherwise} \end{cases}$$

$$\mathcal{R}^i = \begin{cases} \text{PPD_PATH}(P = (c(P), \dots, p_l)) \cup \{a_i\} \\ & \text{if } \exists P \in \mathcal{D}' \text{ with } f(P) = (i, 0) \\ & nul & \text{otherwise} \end{cases}$$

 \mathcal{X} satisfies (a), (b), and (c) in Condition 1 by definition. Moreover, every element of \mathcal{X} contains at most three vertices of G. Thus, it suffices to show that \mathcal{X} satisfies (d) and (e) in Condition 1. By the definition of PPD_PATH and Corollaries 5 and 8, we can observe the following claim.

Claim 21:

- 1. For $1 \leq i \leq m$, $v \in V(C_i) (\{a_{i-1}, a_i\} \cup \{c(P) \mid P \in \mathcal{D}'\})$ appears in consecutive elements of \mathcal{Y}^i .
- 2. For $P \in \mathcal{D}'$, $v \in V(P) \{c(P)\}$ appears in at most two consecutive elements of \mathcal{X} .
- 3. For $0 \le i \le m$, a_i appears consecutive elements of $\mathcal{Y}^i + \mathcal{R}^i + \mathcal{L}^{i+1} + \mathcal{Y}^{i+1}$, where $\mathcal{Y}^0 = \mathcal{R}^0 = \mathcal{Y}^{m+1} = \mathcal{L}^{m+1} = nul$.
- 4. For $P \in \mathcal{D}'$ with f(P) = (i, 1), c(P) appears in the tail of \mathcal{L}^i and in consecutive elements of \mathcal{Y}^i including its head.
- 5. For $P \in \mathcal{D}'$ with f(P) = (i, 0), c(P) appears in the head of \mathcal{R}^i and in consecutive elements of \mathcal{Y}^i including its tail.

It follows from Claim 21 that every vertex in G appears in consecutive elements of \mathcal{X} . Thus, \mathcal{X} satisfies (d) in Condition 1.

It remains to show that \mathcal{X} satisfies (e) in Condition 1. If $X_a \cap X_c = \emptyset$ for all a and c with $1 < a + 1 \le c - 1 < r$, then this is immediate. Thus, we assume that there exist a and c with $1 < a + 1 \le c - 1 < r$ such that $X_a \cap X_c \neq \emptyset$. For $1 \le i \le m$, \mathcal{Y}^i is a proper-path-decomposition of C_i . Thus, we have that $|X_a \cap X_c| \le |X_b| - 2$ for any b with a < b < c if there exists i with $1 \le i \le m$ such that both X_a and X_c are elements of \mathcal{Y}^i . Therefore, we assume that there exists no i with $1 \le i \le m$ such that both X_a and X_c are elements of \mathcal{Y}^i . It follows from assumption and Claim 21 that $X_a \cap X_c$ contains at most one vertex in A and at most one vertex in A and at

Claim 22: $|X_a \cap X_c| = 1$.

Proof: It suffices to show that both a_i $(0 \le i \le m)$ and c(P) are not contained in $X_a \cap X_c$. We prove this by contradiction. Assume that there exist i $(0 \le i \le m)$ and $P \in \mathcal{D}'$ such that $\{a_i, c(P)\} \subseteq X_a \cap X_c$. By

Claim 21 and the assumption that no \mathcal{Y}^i $(1 \leq i \leq m)$ contains both X_a and X_c , we have that f(P) = (i,0) or f(P) = (i+1,1). We may assume without loss of generality that f(P) = (i,0). Then, both X_a and X_c are elements of $\mathcal{Y}^i + (\text{the head of } \mathcal{R}^i)$. Suppose that $\mathcal{Y}^i = (Y_1^i, \ldots, Y_r^i)$. Since $c - a \geq 2$, we have that $X_a \neq Y_r^i$. Thus, there exists j with $1 \leq j < r$ such that $\{a_i, c(P)\} \subseteq X_a = Y_j^i$. However, this is impossible since $(a_i, c(P)) = e_i^0 \in E(G[Y_r^i]) - E(G[\bigcup_{1 \leq j < r} Y_j^i])$ by Corollary 8.

Claim 23: $|X_b| = 3$ for any b with a < b < c.

Proof: Let b be any integer such that a < b < c. If there exists i $(1 \le i \le m)$ such that X_b is an element of \mathcal{Y}^i and that $C_i \in \mathcal{H}$, then $|X_b| = 3$ by Corollary 8. If there exists i $(1 \le i \le m)$ such that X_b is an element of \mathcal{L}^i or \mathcal{R}^i , then $|X_b| = 3$ by the definition of PPD_PATH and by the fact that $|V(P)| \ge 2$ for any $P \in \mathcal{D}'$. Thus, it suffices to show that X_b is not an element of \mathcal{Y}^i such that $C_i \in \mathcal{T} \cup \mathcal{P}$. We prove this by contradiction. Assume that X_b is an element of \mathcal{Y}^i $(1 \leq i \leq m)$ such that $C_i \in \mathcal{T} \cup \mathcal{P}$. It follows from the assumption and Claim 22 that either $X_a \cap X_c = \{a_{i-1}\}$ or $X_a \cap X_c = \{a_i\}$. We assume without loss of generality that $X_a \cap X_c = \{a_i\}$. Since X_b is an element of \mathcal{Y}^i, X_a is an element of \mathcal{Y}^i except the tail. This means that a_i is contained in an element of \mathcal{Y}^i except the tail. However, this is impossible since a_i is an end-vertex of 2-spine of C_i and a_i appears only in the tail of \mathcal{Y}^i by Corollary 5.

It follows from Claims 22 and 23 that $|X_a \cap X_c| - |X_b| = 3 - 2 = 1$ for a < b < c. Thus, \mathcal{X} satisfies (e) in Condition 1.

Therefore, \mathcal{X} is a 2-proper-path-decomposition of G and the proof of sufficiency for Theorem 1 is completed.

We describe in Fig. 5 Algorithm PPD_GENERAL based on Theorem 1. It is well-known that we can find all blocks of a graph in linear time. Moreover, we can determine if a given graph is outer planar in linear time [4]. To find a_0 and a_m in step 3, we need an algorithm to find a 2-spine of a binary tree, which has not been described yet. Although the details are not mentioned here, this can be done in linear time by using a simple postorder searching and the algorithm in [8], which outputs, for a rooted binary tree, the proper-pathwidth of every subtree rooted at a vertex. The other operations in PPD_GENERAL clearly executed in linear time.

Acknowledgment

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The authors are grateful to Professor Y. Kajitani for his encouragement. The authors are also grateful to Dr. A. Takahashi for helpful discussions. The research is a part of CAD21 project at TIT.

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Input: a connected graph G with \Delta(G) \leq 3:
   Output: a 2-proper-path-decomposition of G;
   1. let \mathcal{H}, \mathcal{T}, and \mathcal{P} be the sets of 2-connected components,
        tree components, and path components of G, respectively;
   2. \mathcal{D} := \mathcal{H} \cup \mathcal{T} \cup \mathcal{P};
   3. find a sequence C = (C_1, C_2, \dots, C_m) of components in \mathcal{D}
        and a sequence \mathcal{A} = (a_0, a_1, \dots, a_m) of vertices of G such
        that Condition 2 and the following conditions are satisfied:
                 \deg_G(a_0) = 1 \text{ if } C_1 \in \mathcal{T};
                 \deg_G(a_m) = 1 \text{ if } C_m \in \mathcal{T};
   4. if C and A do not exist then reject;
   5. \mathcal{D}' := \mathcal{D} - \{C_i \mid 1 \le i \le m\};
   6. for each C_i \in H do
           a. find distinct edges e_i^0 \in \Gamma_{C_i}(a_i) and e_i^1 \in \Gamma_{C_i}(a_{i-1}) such that, if there exists P \in \mathcal{D}' with f(P) = (i,j)
                then e_i^j = (a_{i-j}, c(P)) \ (j = 0, 1);
        endfor;
   7. for i = 1 to m do
           a. if C_i \in \mathcal{T} \cup \mathcal{P} then
                \mathcal{Y}^i := \mathtt{PPD\_TREE}(C_i, \mathtt{path}\ (a_{i-1}, \ldots, a_i));
                else \mathcal{Y}^i := PPD\_2CG(C_i, e_i^1, e_i^0);
           b. if \exists P \in \mathcal{D}' with f(P) = (i, 1) then
                \mathcal{L}^i := \mathtt{PPD\_PATH}(P = (p_0, \dots, c(P))) \cup \{a_{i-1}\};
                else \mathcal{L}^i := nul;
           c. if \exists P \in \mathcal{D}' with f(P) = (i, 0) then
                \mathcal{R}^i := \mathtt{PPD\_PATH}(P = (c(P), \dots, p_l)) \cup \{a_i\};
                {\tt else} \; \mathcal{R}^i := nul;
   8. return \sum_{1 \leq i \leq m} \mathcal{L}^i + \mathcal{Y}^i + \mathcal{R}^i;
End
```

Procedure PPD_GENERAL (G)

Fig. 5 Algorithm for constructing a 2-proper-path-decomposition of a general graph.

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